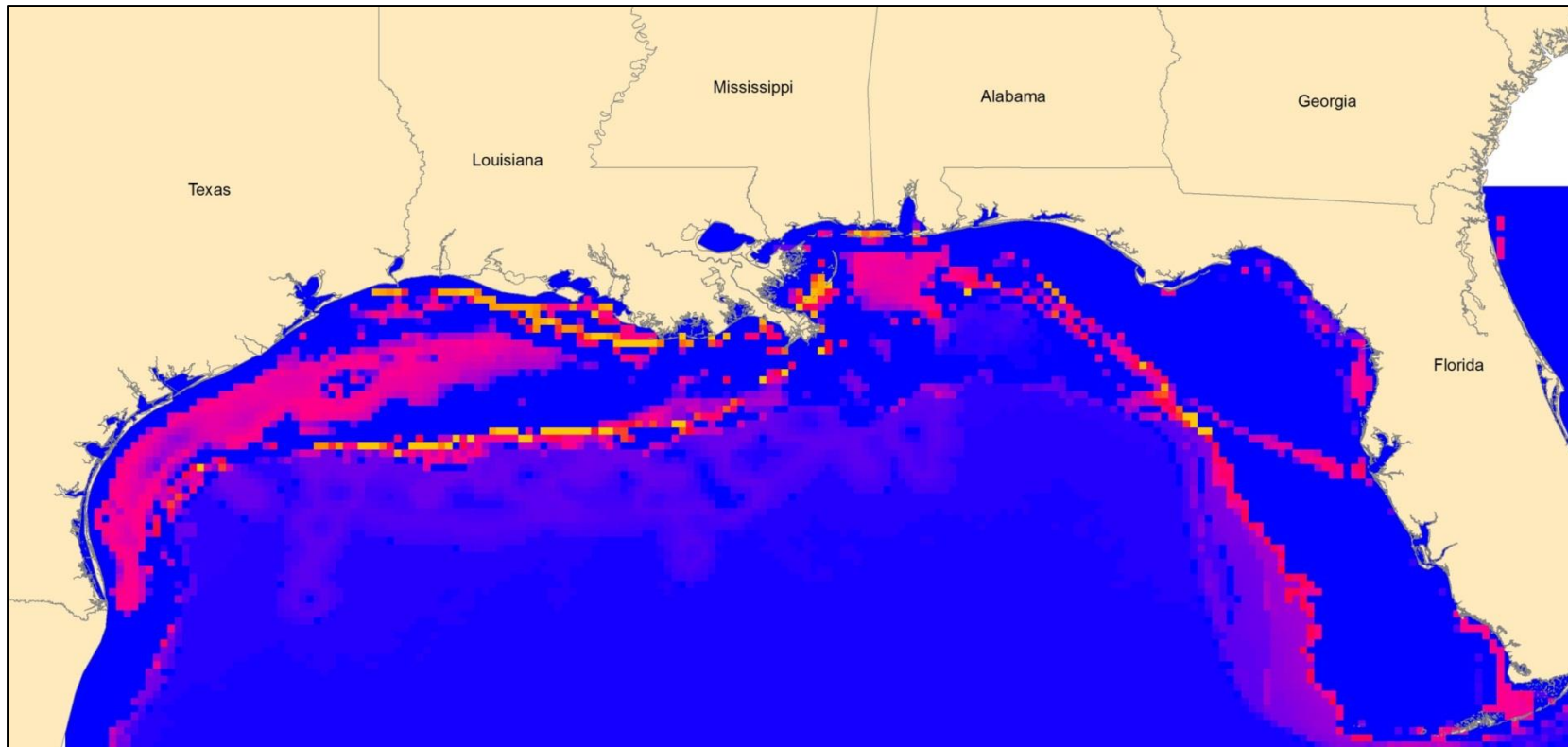
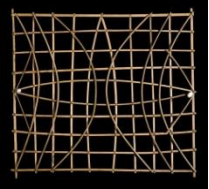


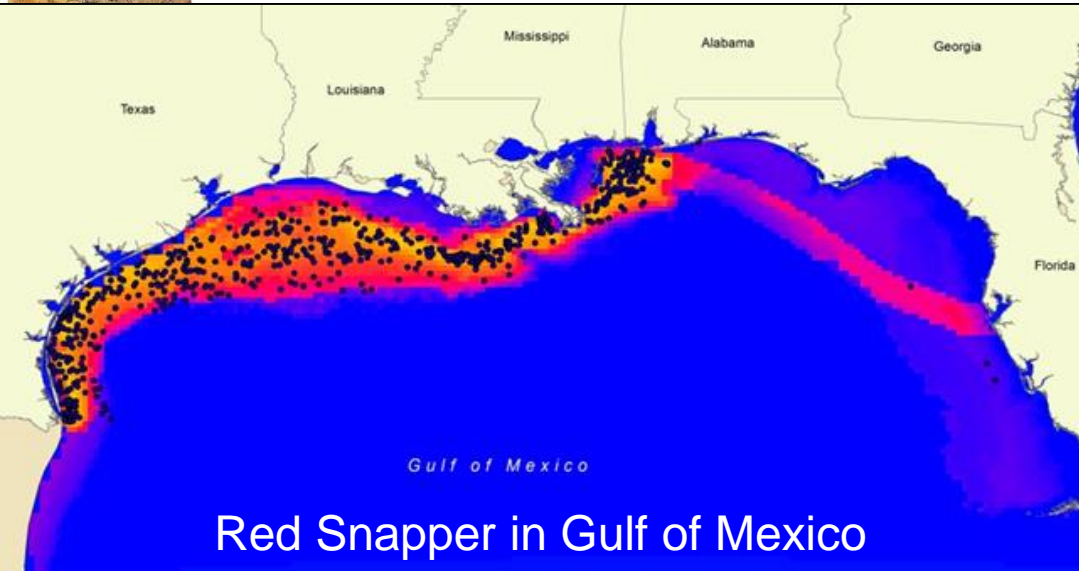
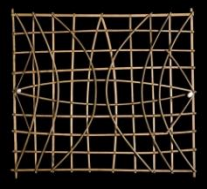
Managing Uncertainty in Habitat Suitability Models

Jim Graham and Jake Nelson
Oregon State University

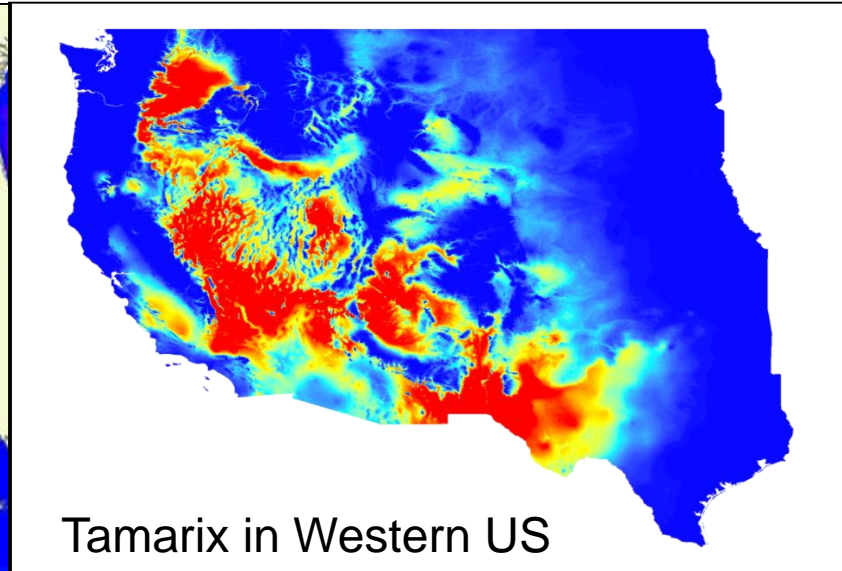


Habitat Suitability Modeling (HSM)

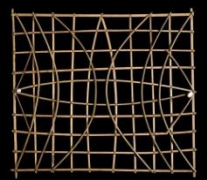
- Also known as:
 - Ecological Niche Modeling (ENM)
 - Species Distribution Modeling (SDM)



Red Snapper in Gulf of Mexico



Tamarix in Western US



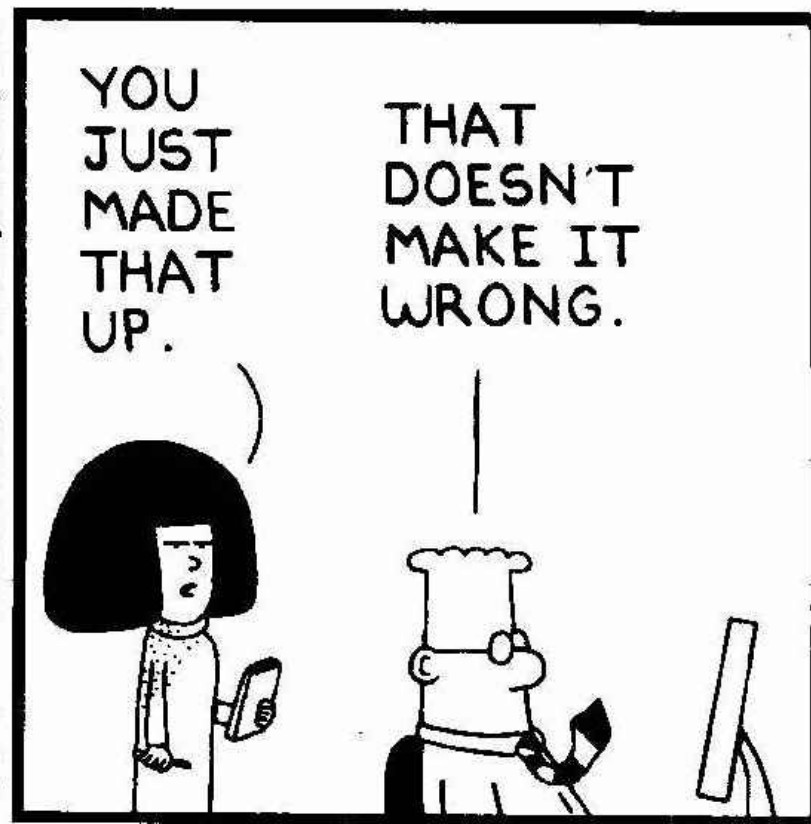
Uncertainty



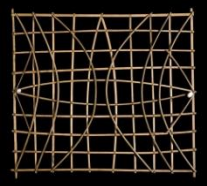
- How “certain” of the data are we?
- How much “error” does it contain?
- How well does the model match reality?
- Goal:
 - Understand and document uncertainties from data collection to publication



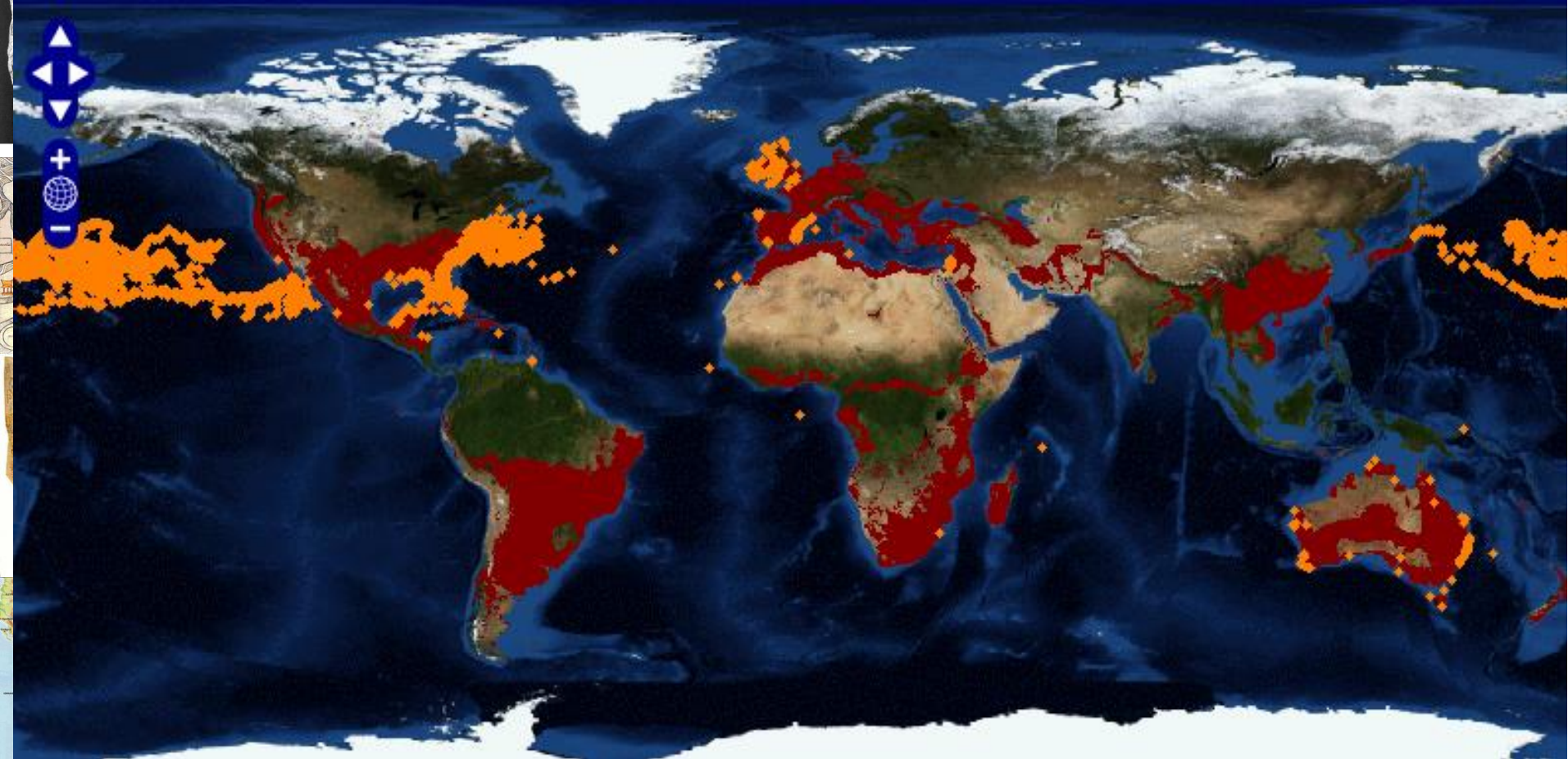
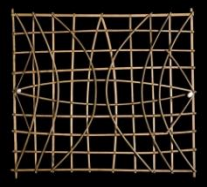
8/6/03 © 2003 United Feature Syndicate, Inc.



LifeMapper: *Tamarix chinensis*



LifeMapper: Loggerhead Turtles



Where to find Bigfoot in Redwood National Park



Introduction

Redwood National Park is located in northern California in both Del Norte and Humboldt counties. Since 1957, there have been a total of 69 reported incidents and/or encounters with Bigfoot in both counties. Thus, the park is likely to be home to a thriving Bigfoot population.



Background – What is a Bigfoot?

"The term "sasquatch" is an anglicized derivative of the word "Sésquac", meaning "wild man". The original word, in the Stó:lō dialect of the Halkomelem language, is used by the Coast Salish Indians of the Fraser Valley and parts of Vancouver Island, British Columbia.

Indian tribes across North America have a total of more than sixty different terms for the sasquatch.

"Bigfoot" was a journalistic term generated in the middle of the last century during a rash of sightings in Northern California. The word has come to be recognized widely.

Many different terms have been used by pioneers and later non-native inhabitants of North America, including "skookums" and "mountain devils".

From www.bfro.net, "What is a Bigfoot, or Sasquatch?"

Objective

To determine where the most likely places to see Bigfoot are in order to aid The Bigfoot Field Researchers Organization and Bigfoot enthusiasts in their quests to find Bigfoot.

Assumptions

Bigfoot prefer dense canopy cover, nearby sources of water and shady regions. They don't like people, so they avoid campgrounds and roads, though there have been multiple records where citing occur near and on campgrounds and roads.

Limitations

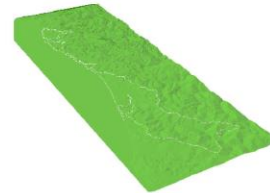
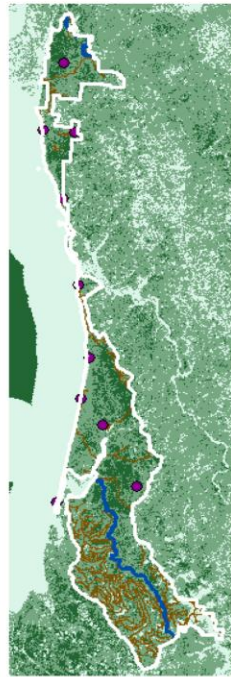
- No detailed layer of stream data
- Hand-plotted campsites subject to human error
- Lack of metadata on collected data layers

Factors

- Campgrounds
- Streams
- Roads
- Canopy
- Aspect

3D Analysis

We built a TIN from a NED elevation model and considered the types of slopes and aspects Bigfoot would feel most comfortable in. After going through a number of accounts, we found that slope does not seem to affect Bigfoots' preferences. Instead, we decided that they preferred shadier areas to hide in and so we found areas with north-facing aspects.



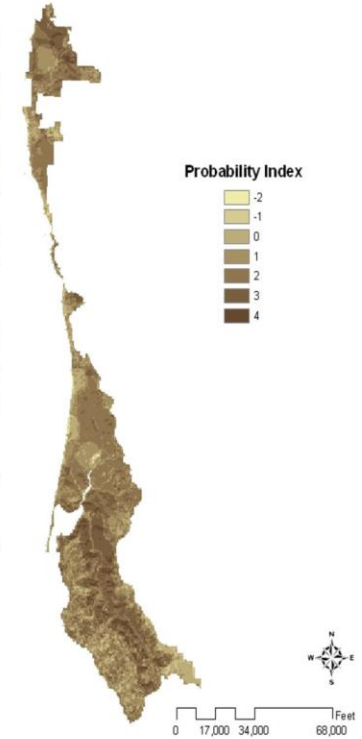
"The lady giving me a ride into town told me to look out my window to the right... I saw a very large hairy creature walking across a wide, dried up creekbed... My friend told me she sees them all the time out there near her home, so it was just a normal thing for her"

- Bigfoot sighting, Del Norte County, January 1979

Suitability Analysis

We created buffers around streams, campgrounds, and roads and assigned opportunity and constraint values to each feature. We then assigned opportunity and constraint values to canopy density and aspect maps. These values were used to create a map of Bigfoot habitat suitability.

Suitability Criteria	
	Values
Opportunities	
Dense canopy layer	
80+	+2
60-80	+1
Less than 60	0
1 mile buffer from major streams	+1
North-facing aspect	+1
Constraints	
200 feet buffer from roads	-1
1 mile radius from campsites	-1



Acknowledgments

Poster & analysis by Amanda Carlson & Katharine Guan, University of California, Berkeley

Data Sources: USGS Seamless Server, atlas.ca.gov, www.bfro.net

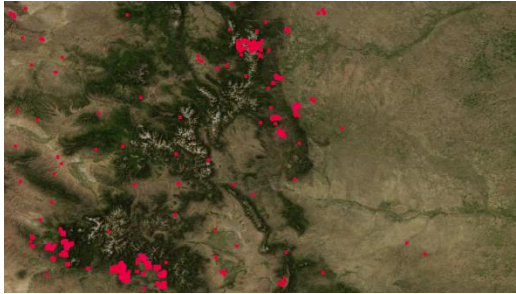
Projection: NAD 1983 California State Plane I (feet)

Conclusion

The most suitable Bigfoot habitats are along Redwood Creek and near the northern border of the park. Areas shaded in dark brown are where you should go to find Bigfoot. However, these probabilities are not very strong and we suggest further analysis on other parks to better find Bigfoot.

HSM Process

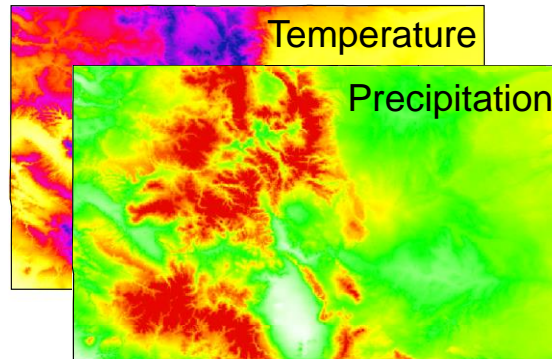
Occurrences (Sample Data)



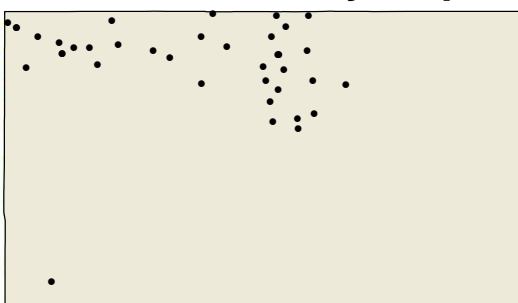
Spreadsheets

Lat	Lon	Temp	Precip
-105.504	40.35819	5.32	58.4
-107.472	40.498	6.31	47.6

Environmental Layers
(Predictors)



Habitat Suitability Map

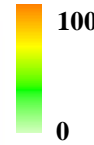


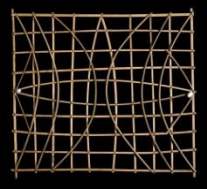
Modeling
Method

Model Parameters

Variable	Param1	Param2
Annual Precip	-0.05	0.0
Annual Temp.	0.61	0.0

Map
Generation



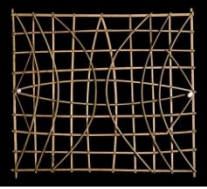


Input Data



- Sample Data:
 - Typically points
 - Usually “Occurrences” or “Observations”
 - Often opportunistic, integrated data
 - Typically of unknown uncertainty
- Predictor layers
 - Environmental factors/characteristics
 - Typically rasters
 - Huge variety
 - Typically of unknown uncertainty

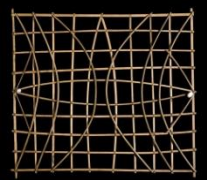




Occurrences of Polar Bears



From The Global Biodiversity Information Facility (www.gbif.org, 2011)



January 1st Dates



- If you put just a “year”, like 2011, into a relational database, the database will return:

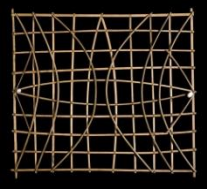
- Midnight, January 1st, of that year

- In other words:

- 2011 becomes:

- 2011-01-01 00:00:00.00



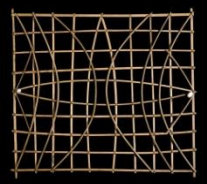


Predictor Layers



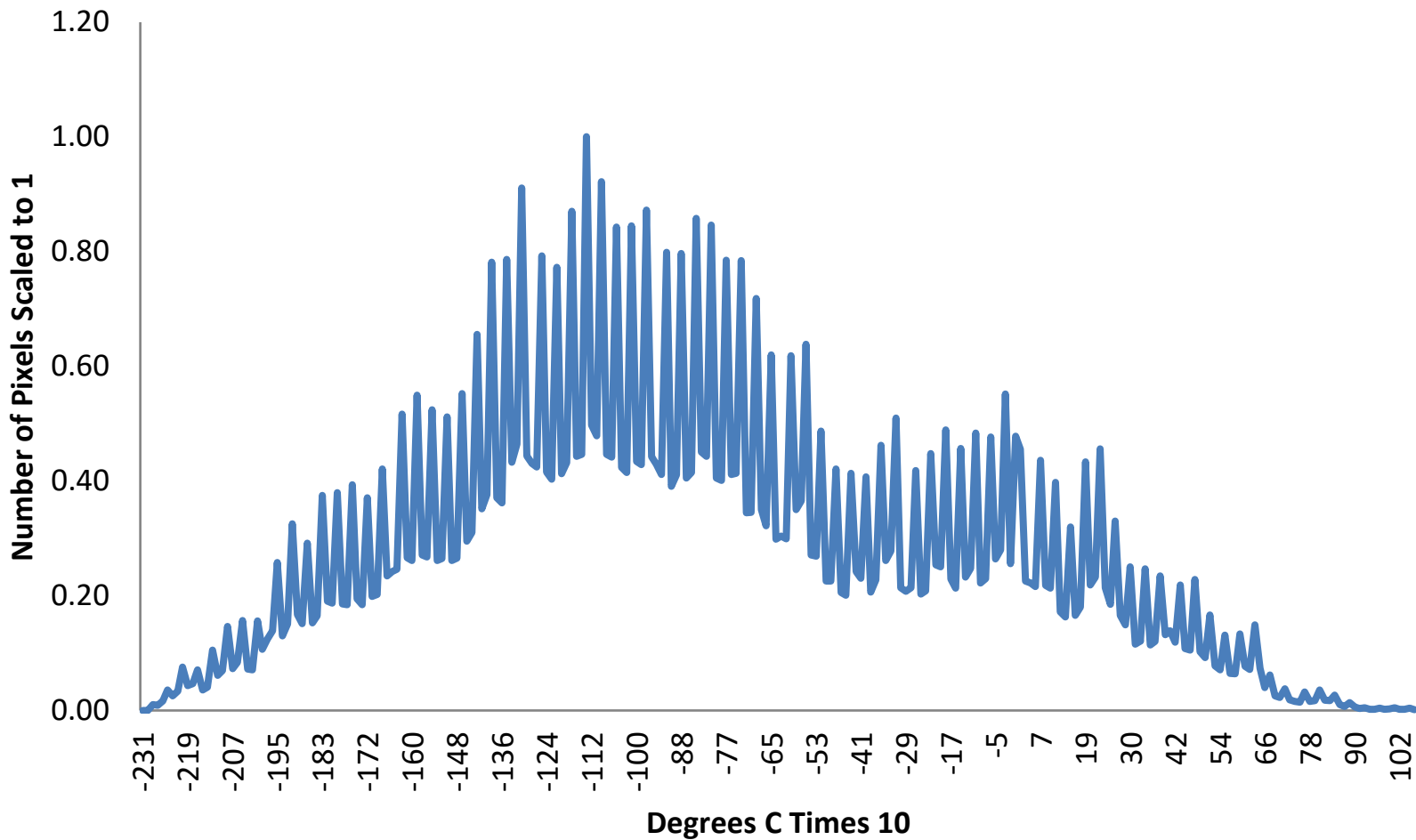
- Remotely sensed:
 - DEMs, Visual, IR, NIR, SST, NPP, Sea Height
- Integrated from multiple data sets:
 - Bathymetry
- Interpolated:
 - Temp, precipitation, wind
 - DO, Sub-surface temp, salinity, bottom type
- Processed from other layers:
 - Slope, aspect, distance to shore
- From other models:
 - Climate



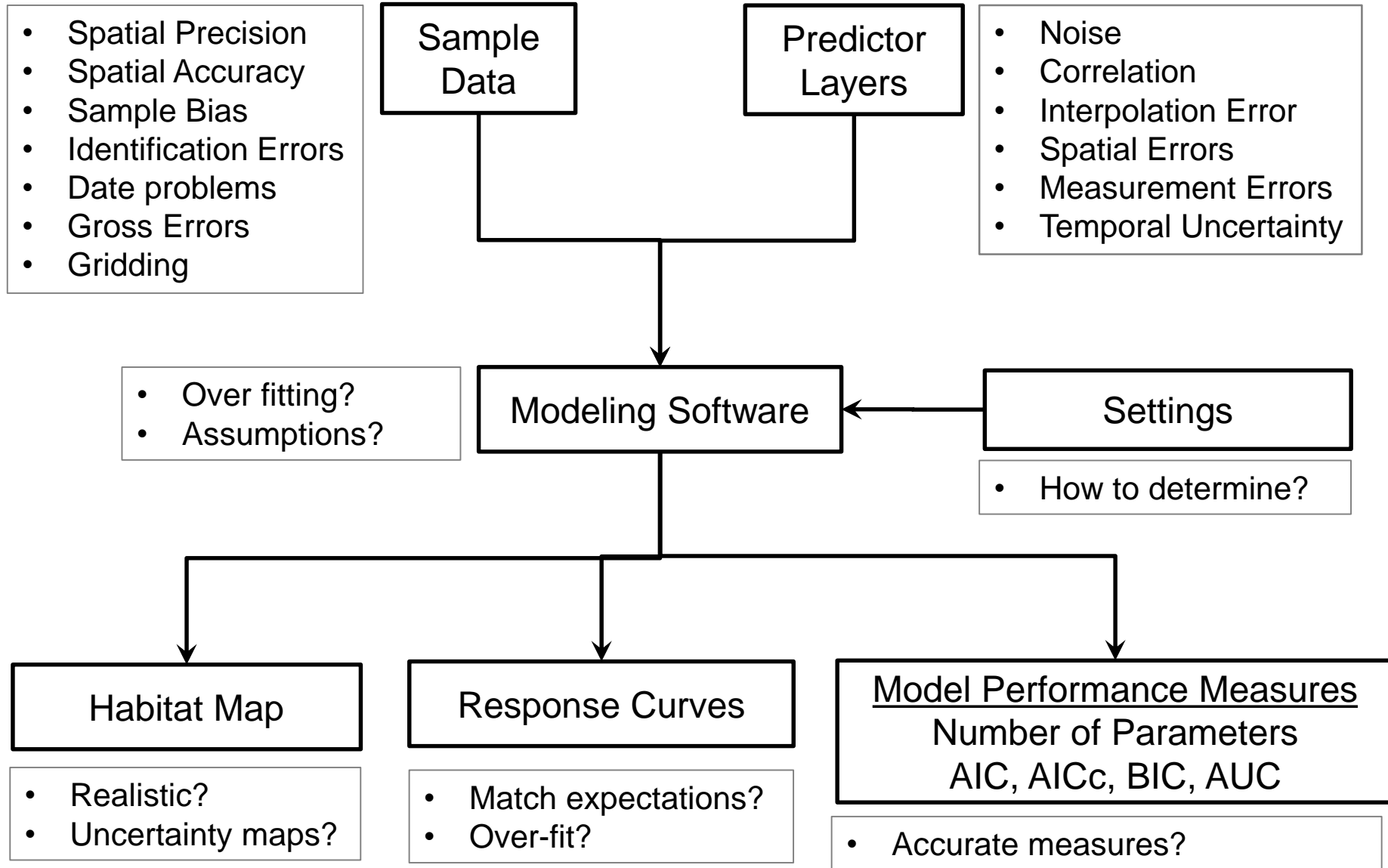


BioClim/WorldClim Data

Min Temp of Coldest Month

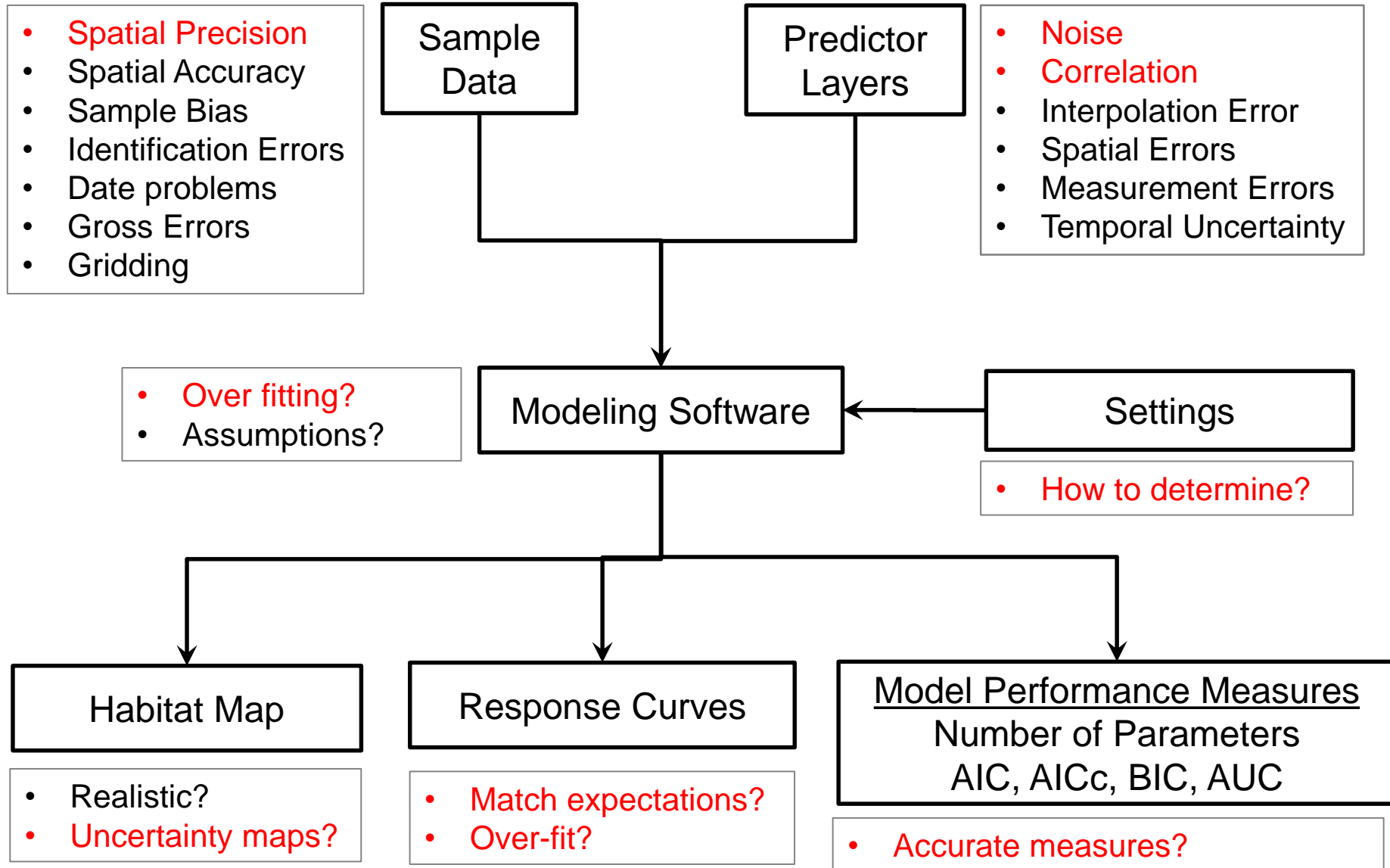


Road Map of Uncertainty



What is the best model?

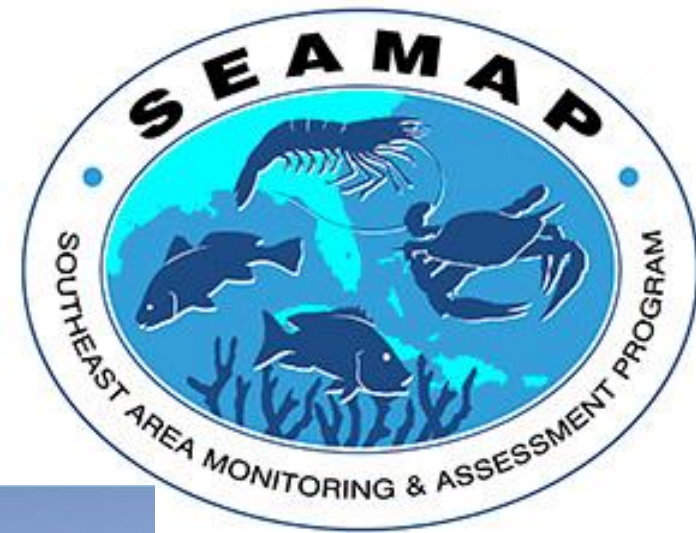
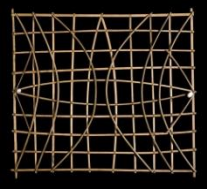
Road Map of Uncertainty

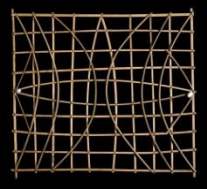


What is the best model?

SEAMAP

- Southeast Area Monitoring and Assessment Program (SEAMAP)
- Over 50 years of data
- Over 40,000 trawls





Red Snapper



- An important recreational and commercial species
- \$7 - 70 million/year

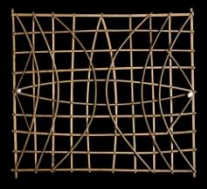


www.safmc.net



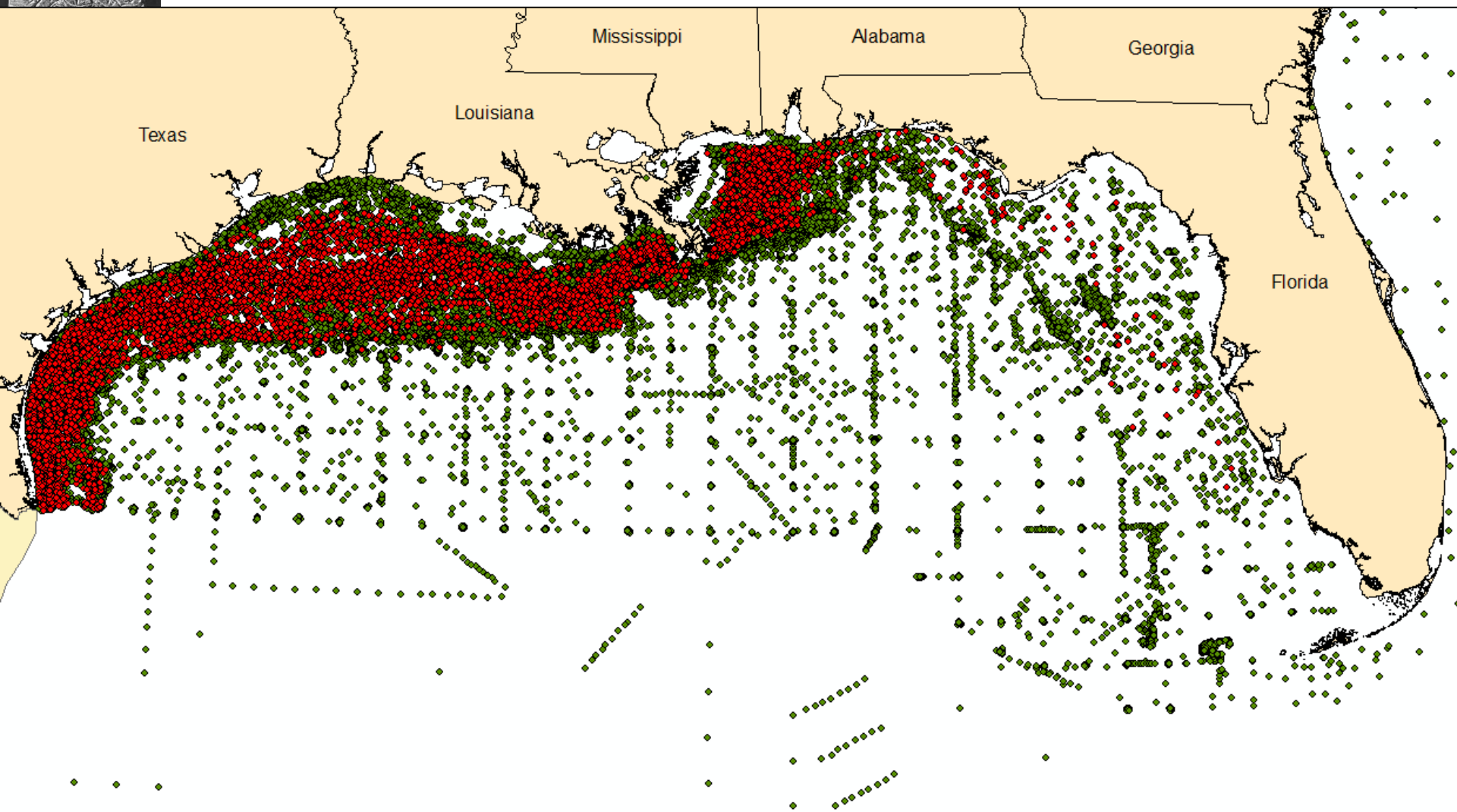
lickyourownbowl.wordpress.com

outdooralabama.com



● SEAMAP Trawls (>47,000 records)

● Red Snapper Occurrences (>6,000 records)



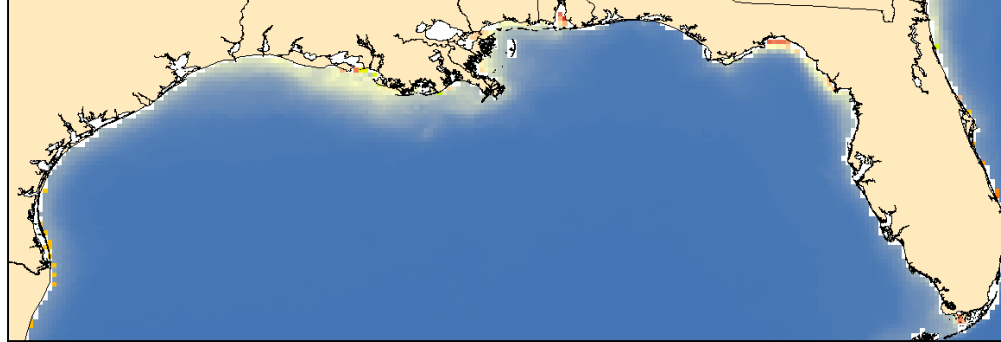
Sea Surface Temperature (SST)

NOAA

AVHRR Pathfinder Satellite

Spatial: 9km

Measured: <0.4 K

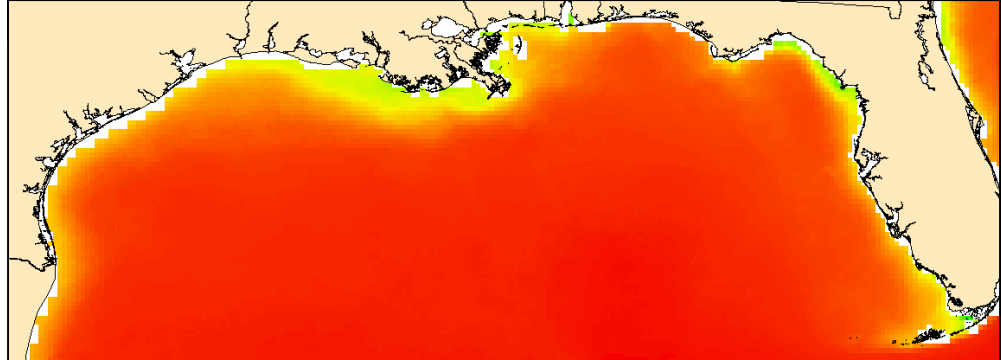


Net Primary Production (NPP)

Milligrams of Carbon per
Meter Squared per Day

OSU Ocean Productivity

Uncertainty?

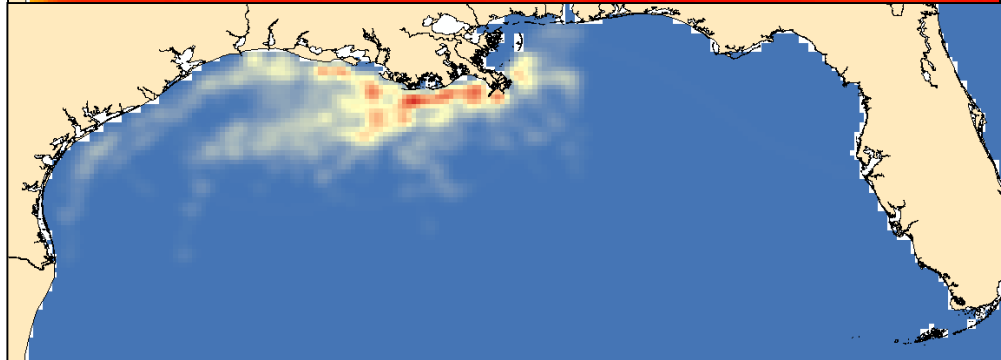


Density of

Platforms and Pipelines

Created from Bureau of Ocean Energy
Management (BOEM) Point Data Set

Uncertainty?



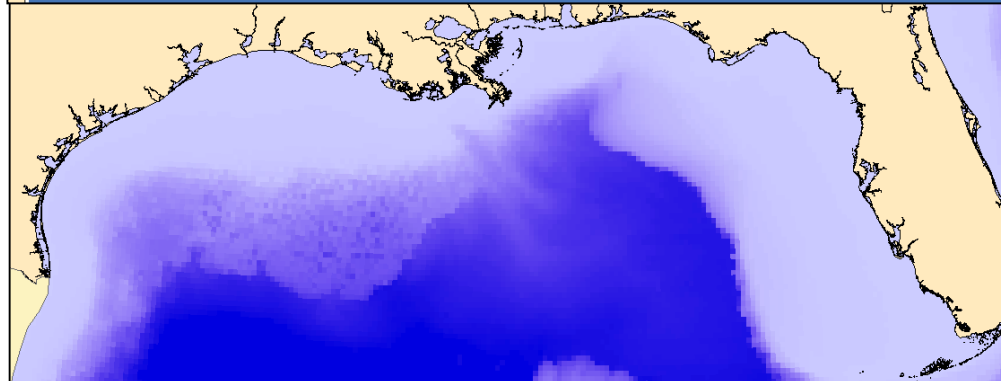
Bathymetry

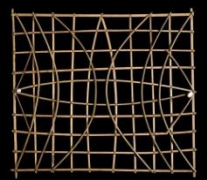
Resampled from 90m

NOAA Coastal Inundation Dataset

And others

Uncertainty < 9km





Predictor Resolution



- Should model at the lowest resolution of the predictor layers or lower

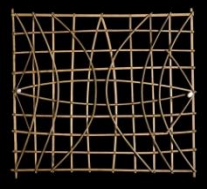


- Lower resolution:
 - Can reduce problems from sample data uncertainty
 - In some cases can combine sample data into measures such as CPUE, density, abundance
 - Reduces detail of final model



- For these tests: 9km





Sample Data

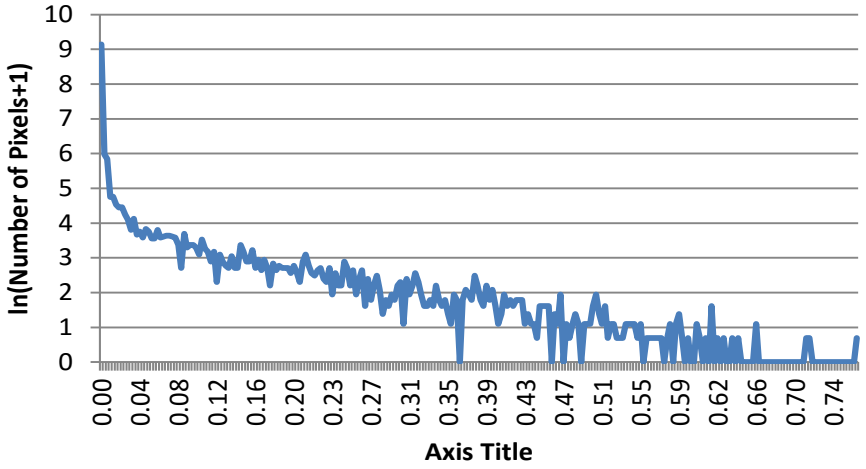


- Spatial Precision
 - Standard Deviation of about 2 km
- Spatial Accuracy:
 - < 1km
- Sampling Bias:
 - Some areas more heavily sampled
- Identification Errors:
 - Unknown but red snapper are pretty easy to identify
- Date problems:
 - Not a temporal model
- Gridding:
 - Not at 9 kilometers

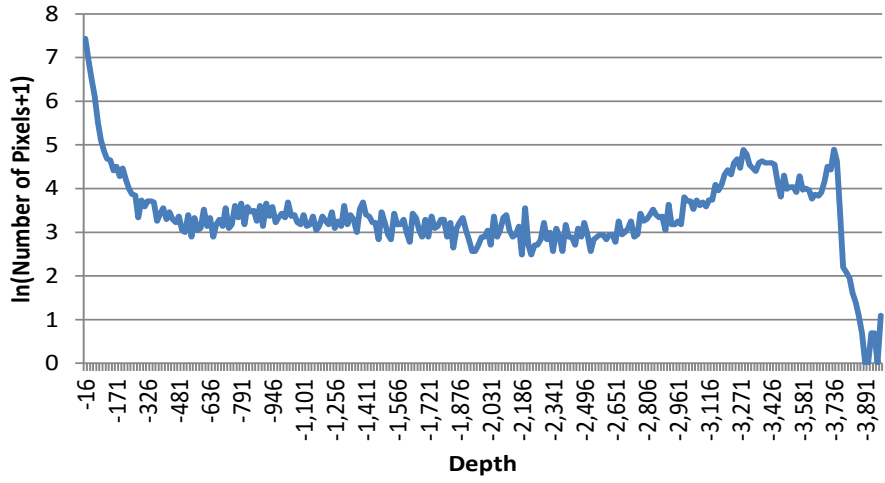


Histograms of Predictor Layers

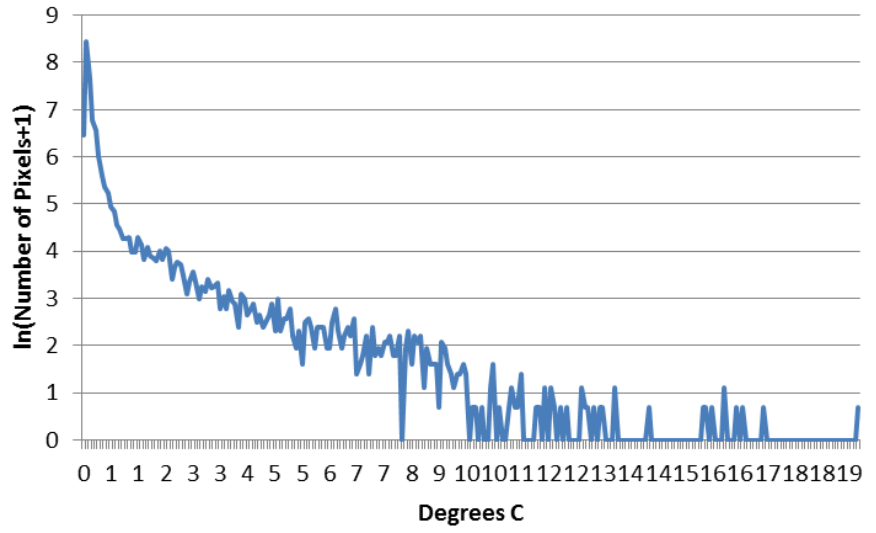
Density of Infrastructure



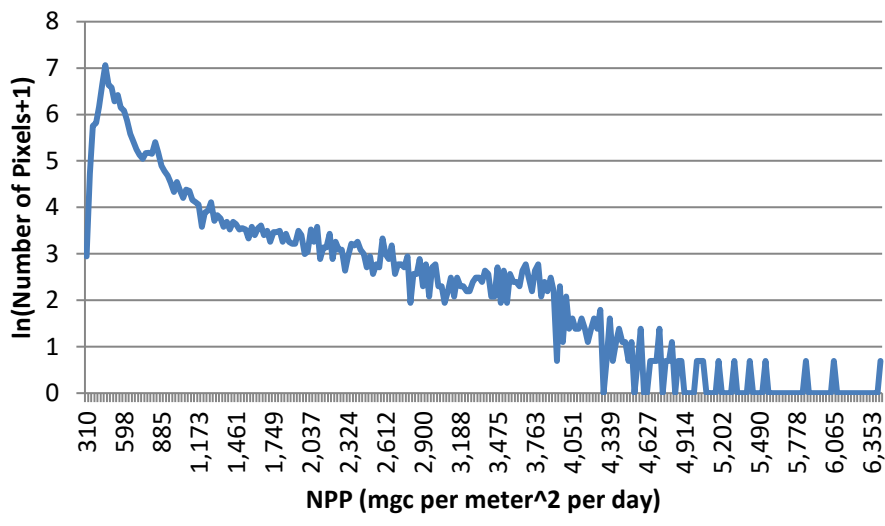
Bathymetry Histogram

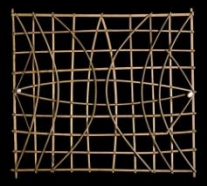


Sea Surface Temperature



Net Primary Productivity Histogram

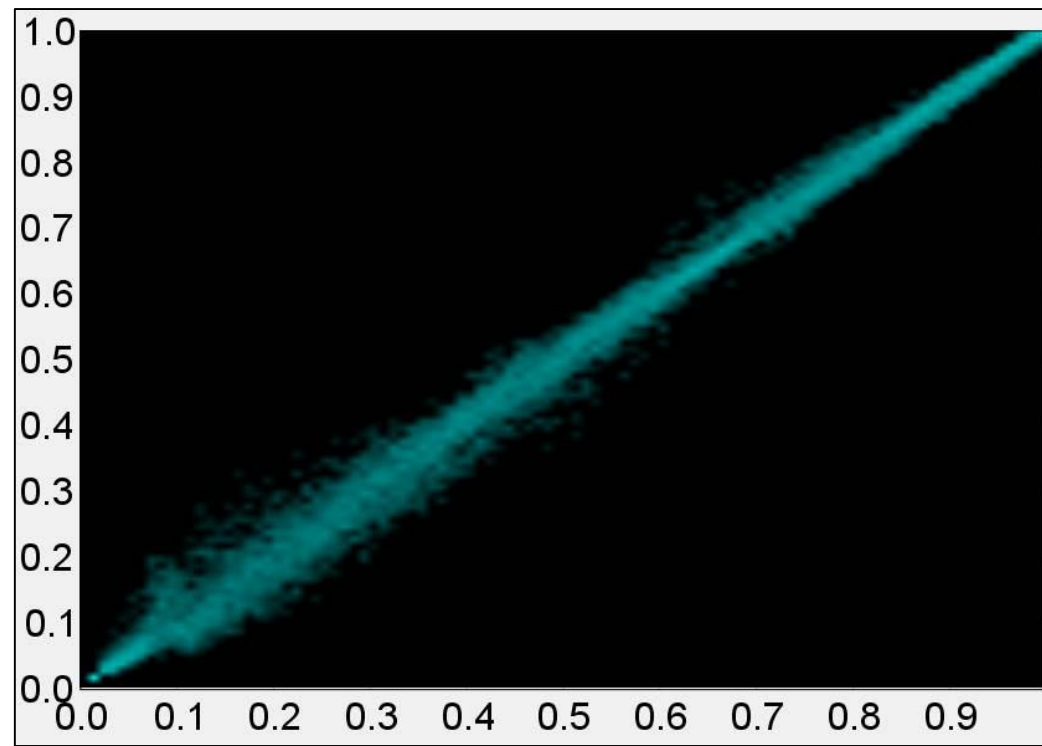


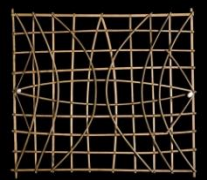


Predictor Layer Uncertainty



- Noise: Minimal
- Correlation: Eliminate NPP
- Spatial Errors: Unknown, $< 9\text{km}$?
- Measurement errors: Minimal to Unknown



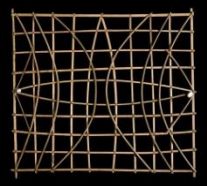
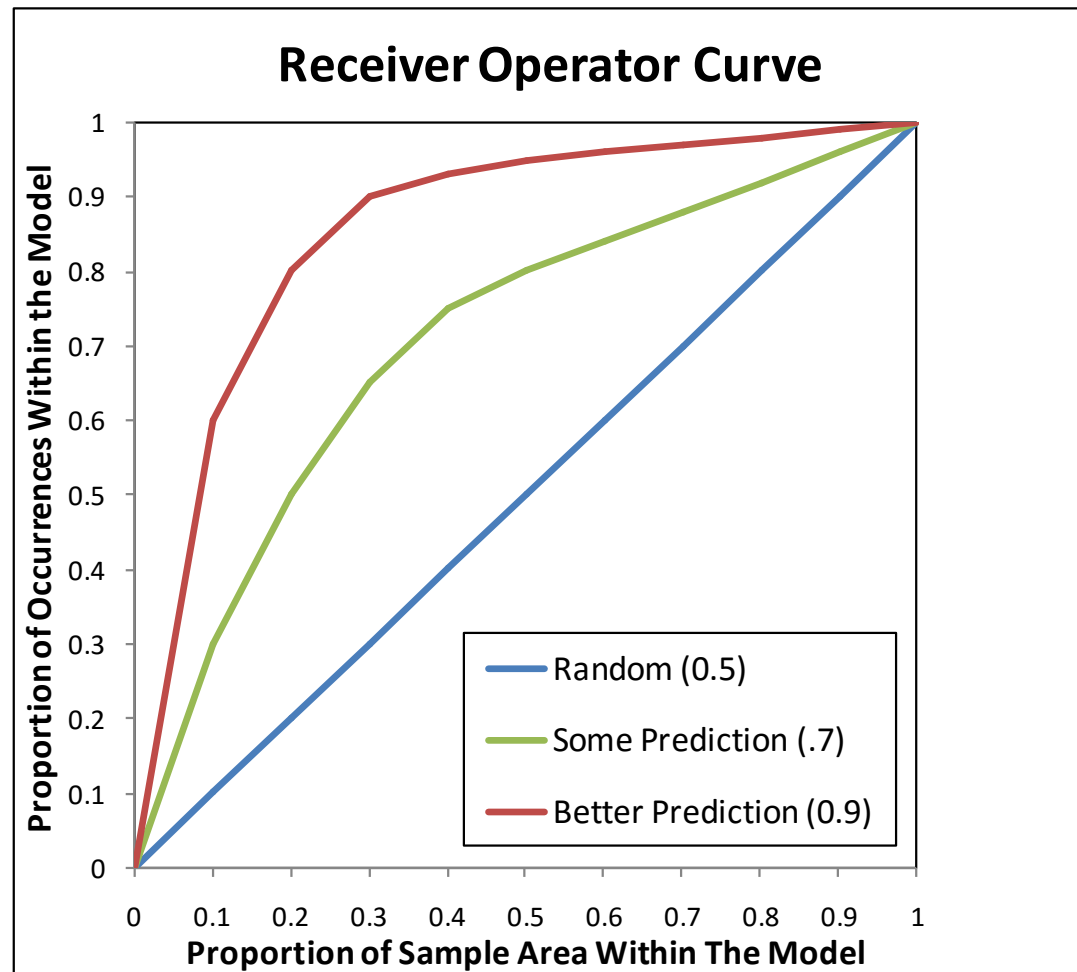


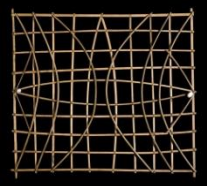
Modeling Software: Maxent

- Popular, relatively easy to use
- Only requires presence points
- **Known for over-fitting**
- Performs “piece-wise” regression
- Assumes:
 - Predictors are error free
 - Independence of errors in response
 - Lack of correlation in predictors
 - Constant variance
 - Random data collection over sample area

Area Under the Curve (AUC)

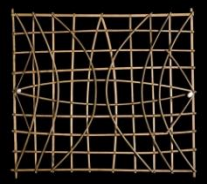
- Area under a Receiver Operator Curve (ROC)
- Popular for HSM
- Encourages over-fitting





Akaike Information Criterion (AIC)

- Balance between complexity:
 - Over fitting or modeling the residuals (errors)
 - Lots of parameters
- And bias
 - Under fitting or the model is missing part of the phenomenon we are trying to model
 - Too few parameters
- Smaller is “better”
- Must be used with the same samples and predictors between models

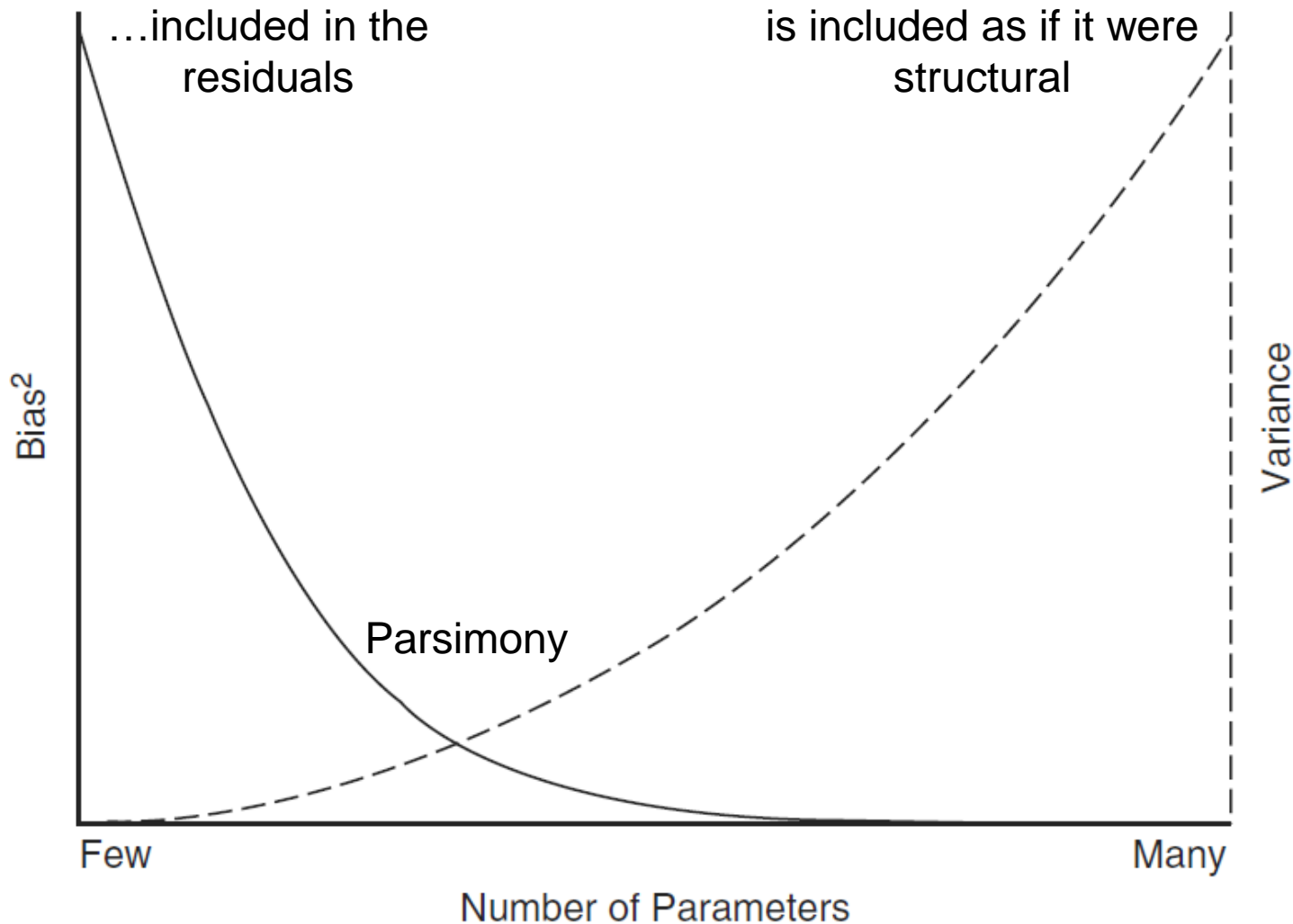


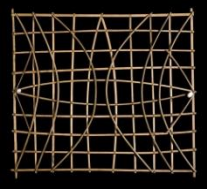
Parsimony



Under fitting
model structure
...included in the
residuals

Over fitting
residual variation
is included as if it were
structural



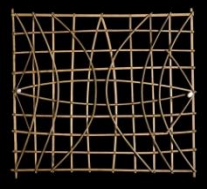


Experiments



- Different regularization multipliers
 - Select regularization for other tests
- Try different numbers of samples
 - Determine the number of samples to use
- “Jiggle” the sample data spatially
 - Introduce different amounts of spatial error

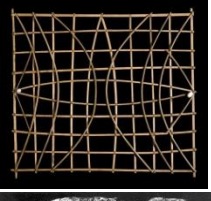




BlueSpray

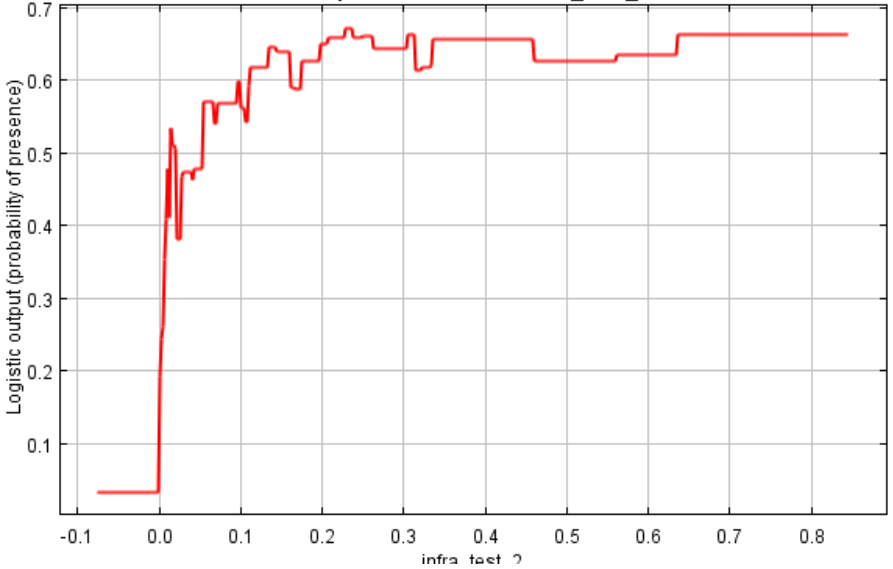


- GIS Application for Natural Resources and Environmental Research
 - Specifically HSM
- Available at www.schoonerturtles.com
- Free for beta testers in environmental research and conservation
- Contact Jim at: jimg@schoonerturtles.com for the passcode

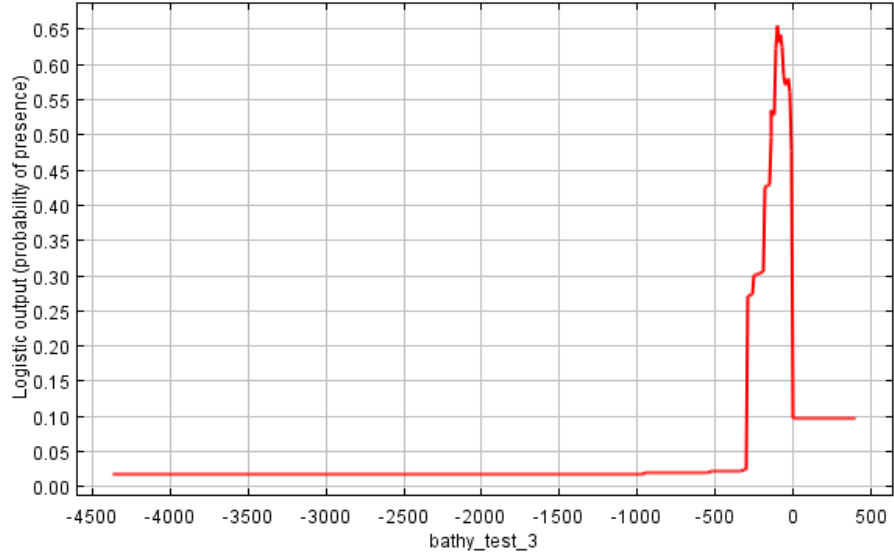


Regularization=0.1

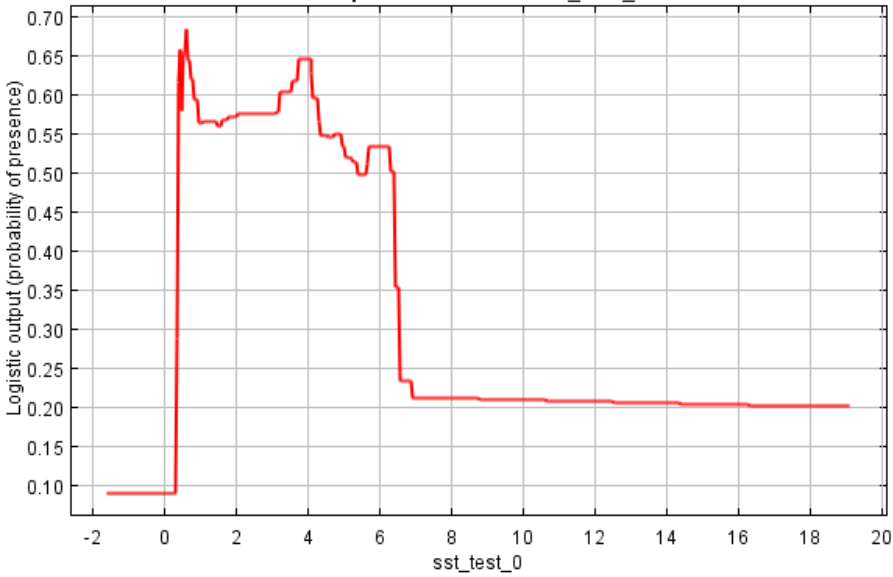
Response of Test to infra_test_2



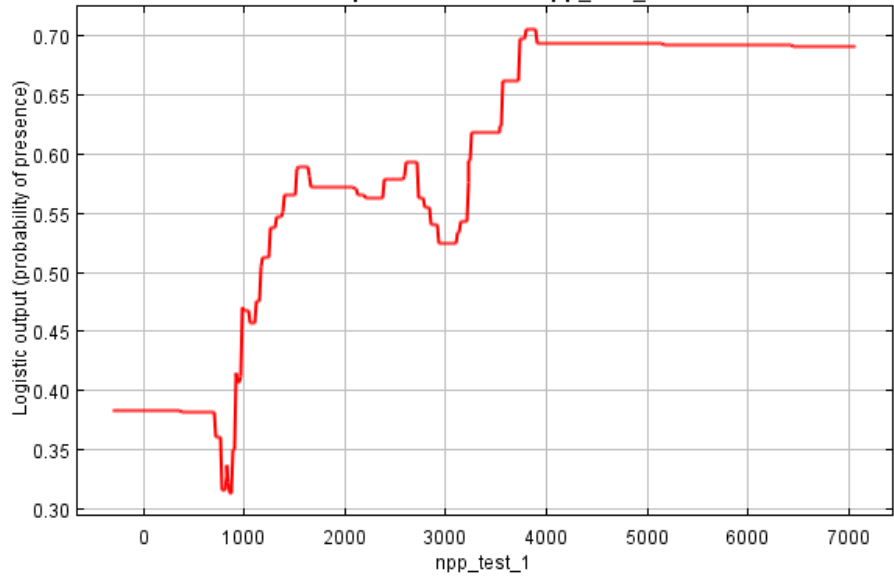
Response of Test to bathy_test_3

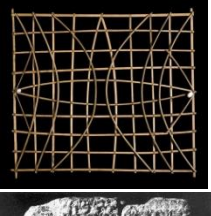


Response of Test to sst_test_0



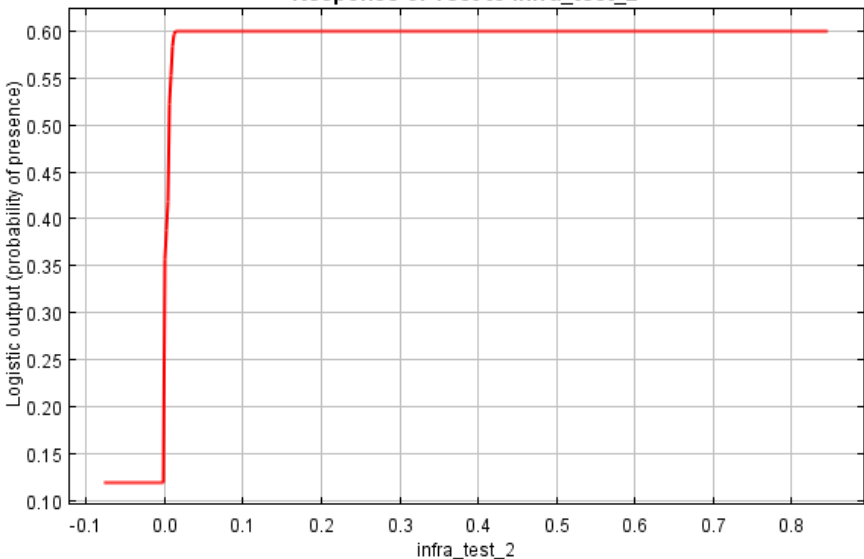
Response of Test to npp_test_1



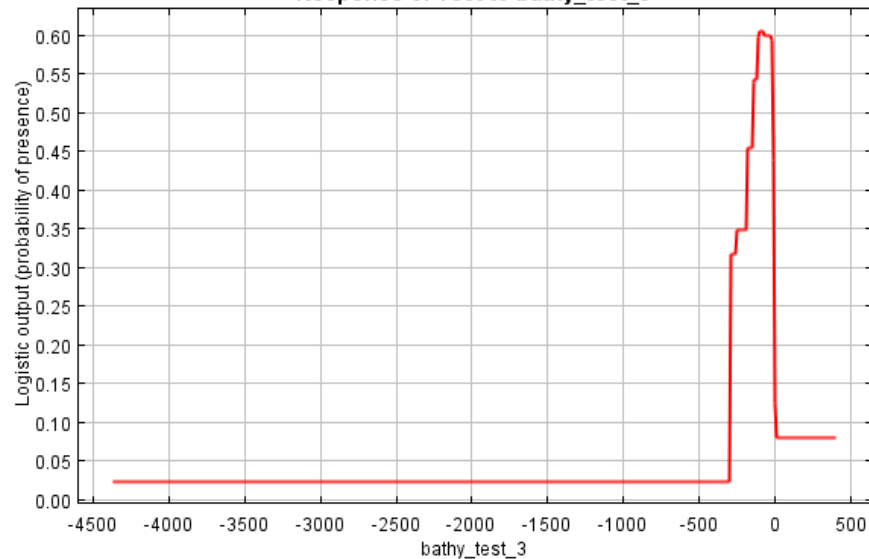


Regularization=1.2

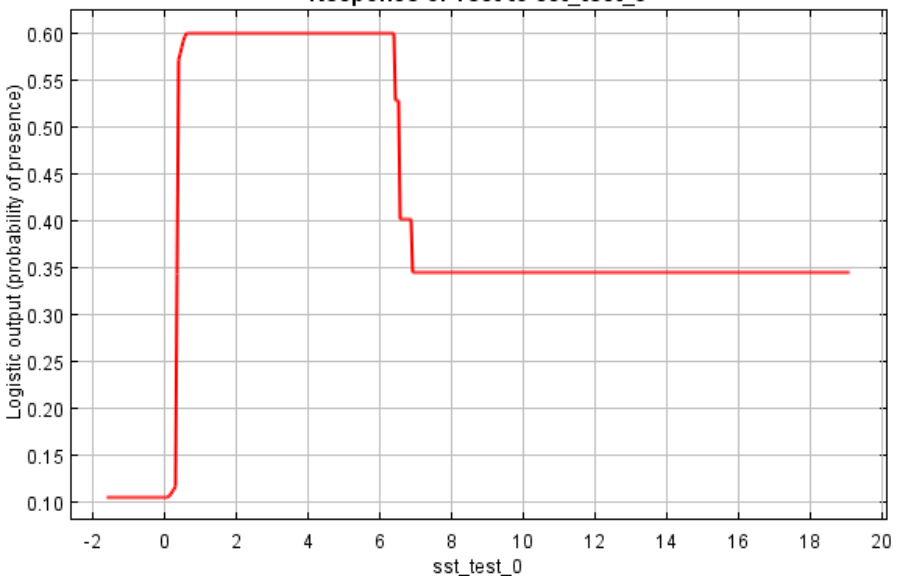
Response of Test to infra_test_2



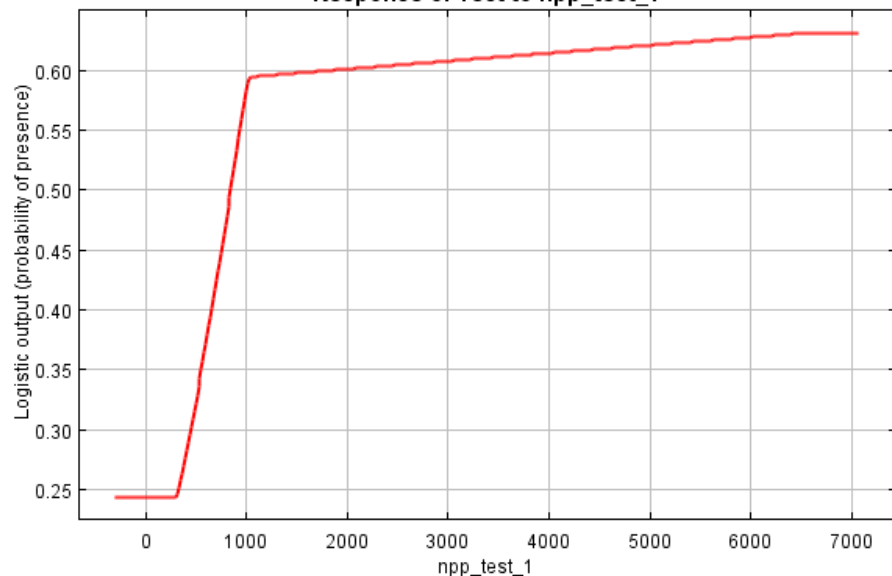
Response of Test to bathy_test_3

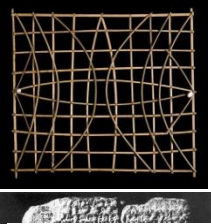


Response of Test to sst_test_0



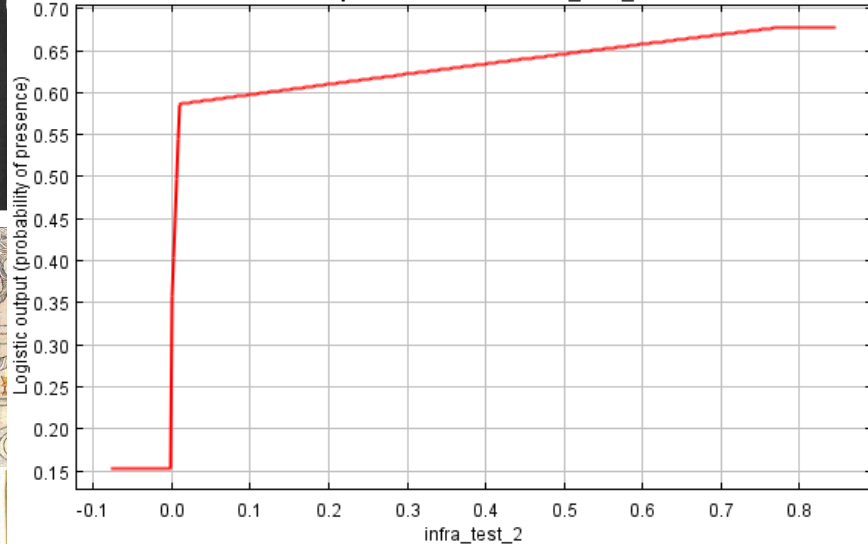
Response of Test to npp_test_1



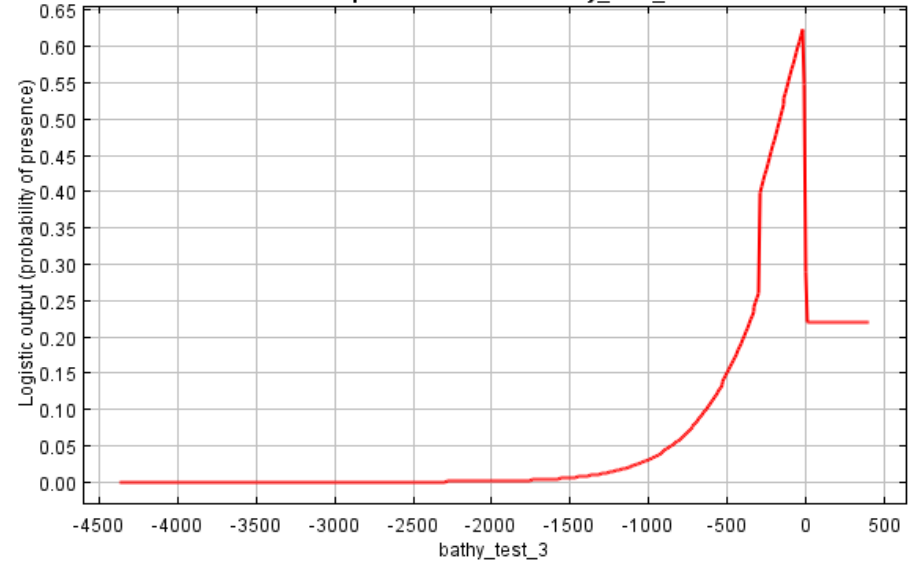


Regularization=10

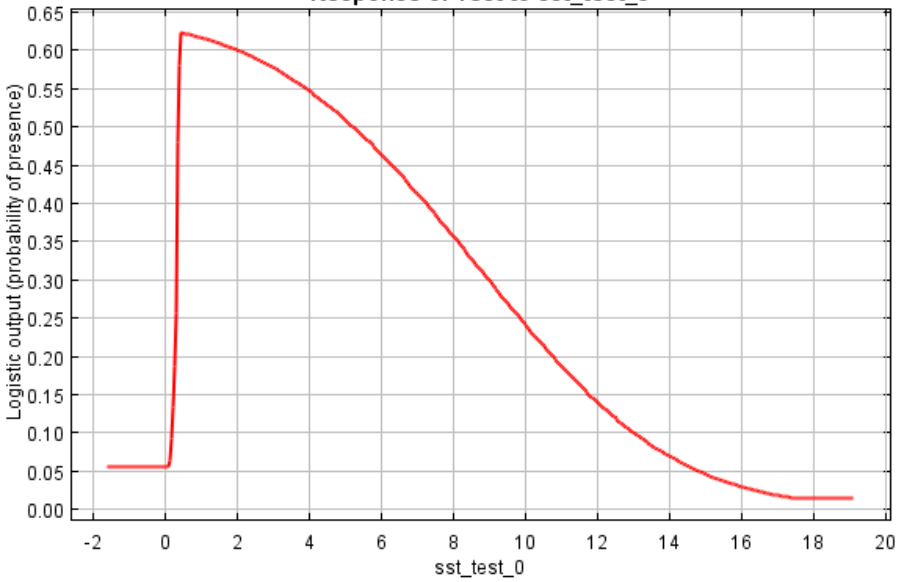
Response of Test to infra_test_2



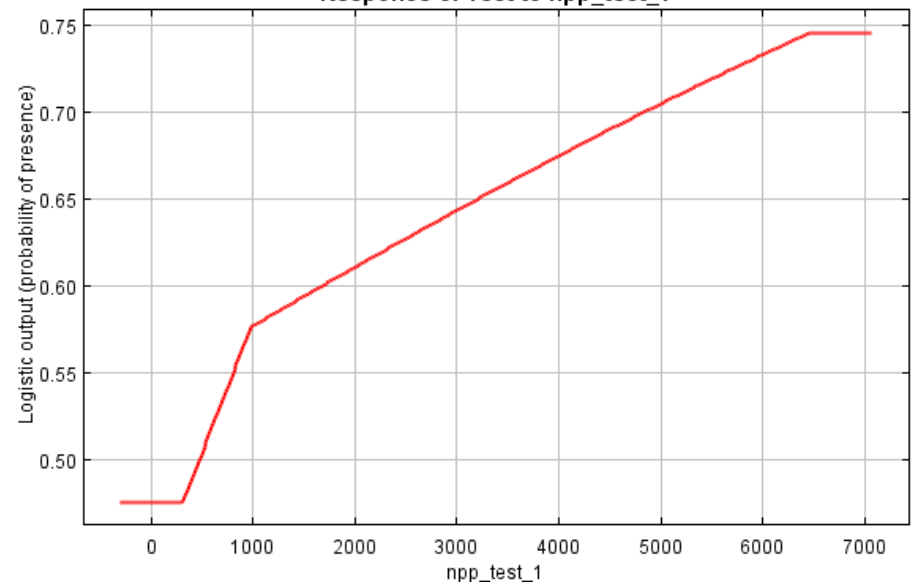
Response of Test to bathy_test_3

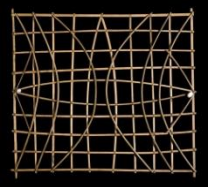


Response of Test to sst_test_0



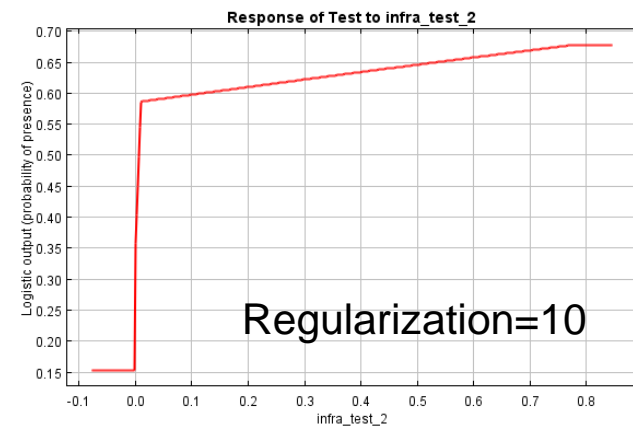
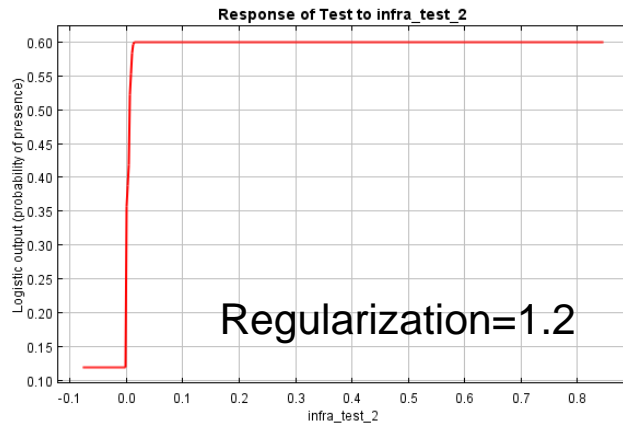
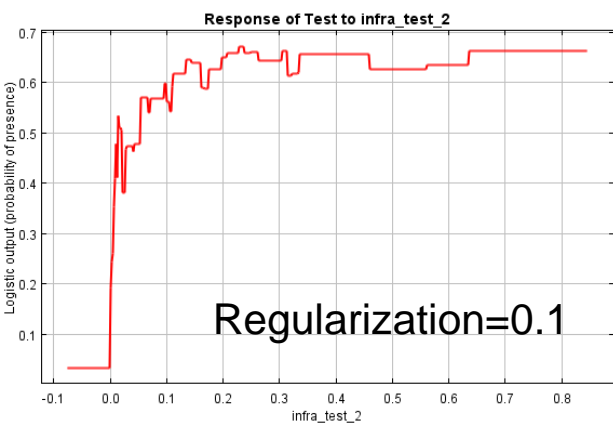
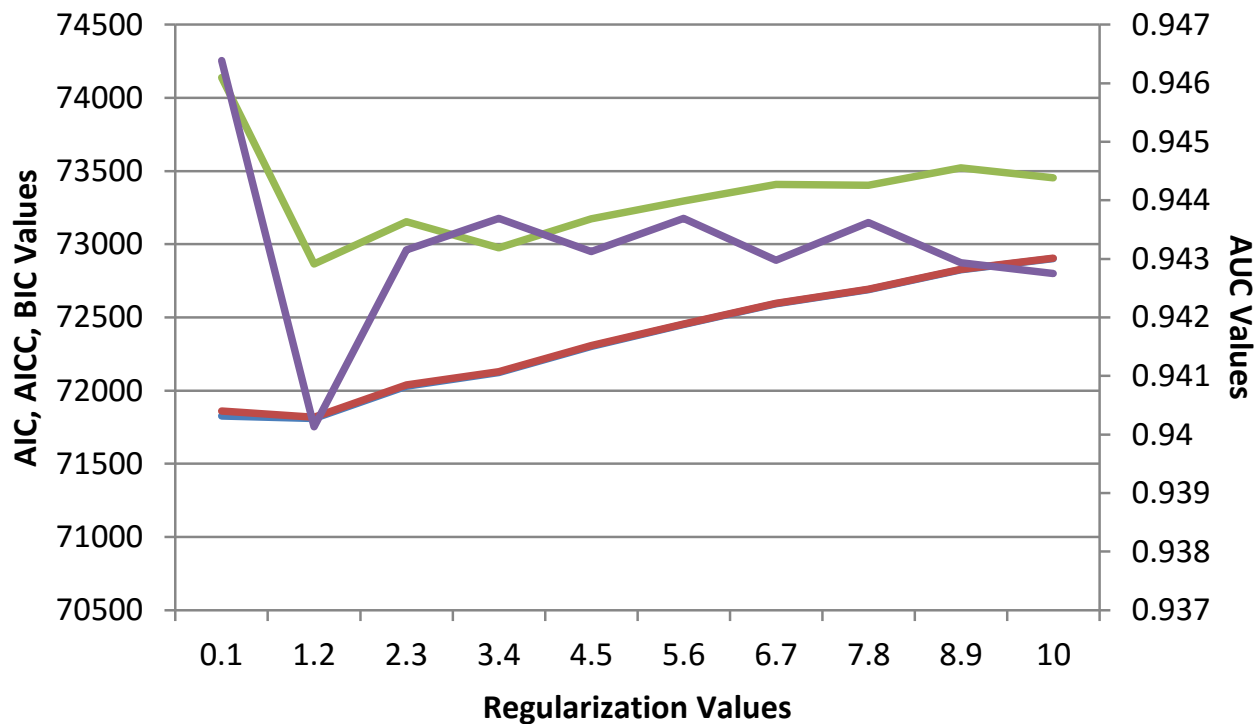
Response of Test to npp_test_1

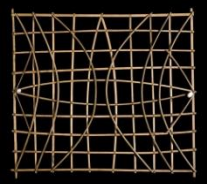




Regularization Results

— AIC — AICC — BIC — AUC





10%
Sample
Points



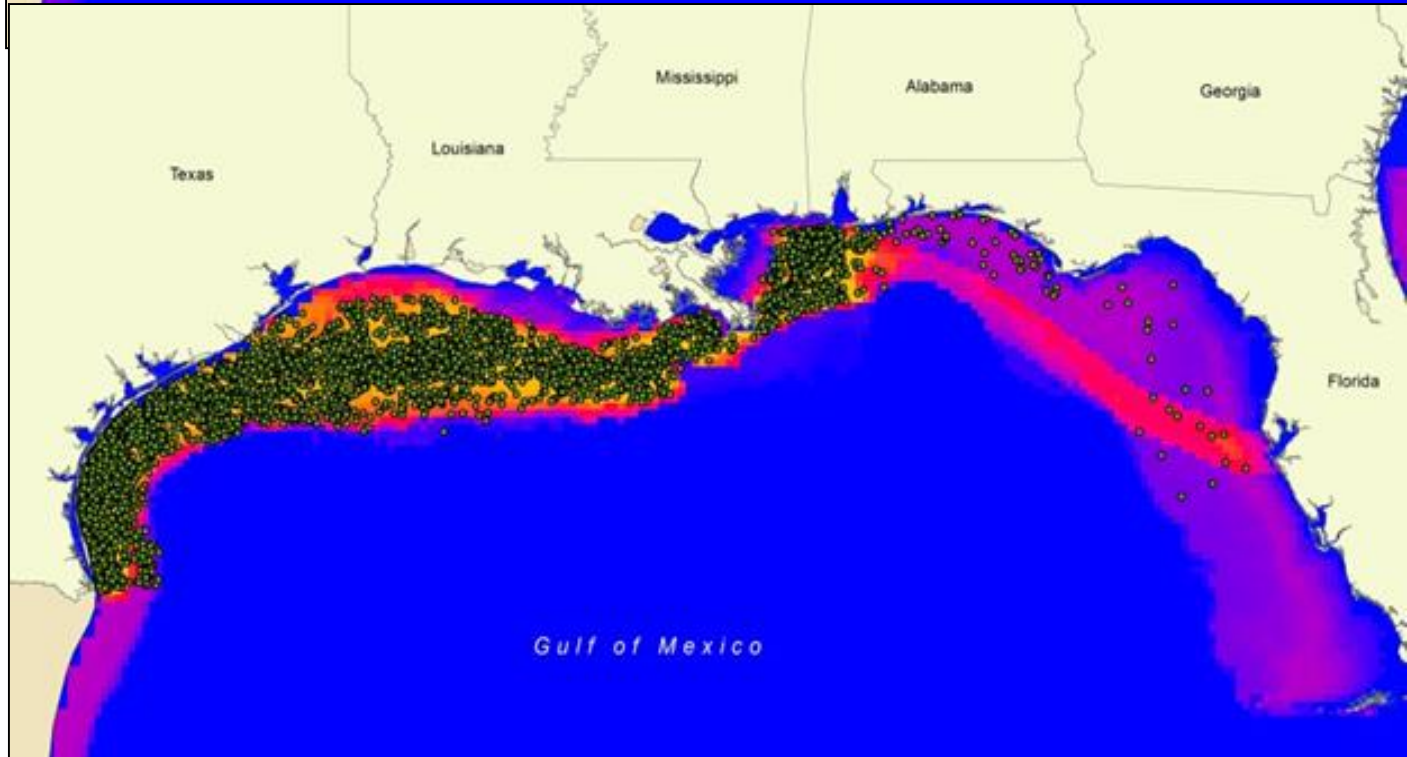
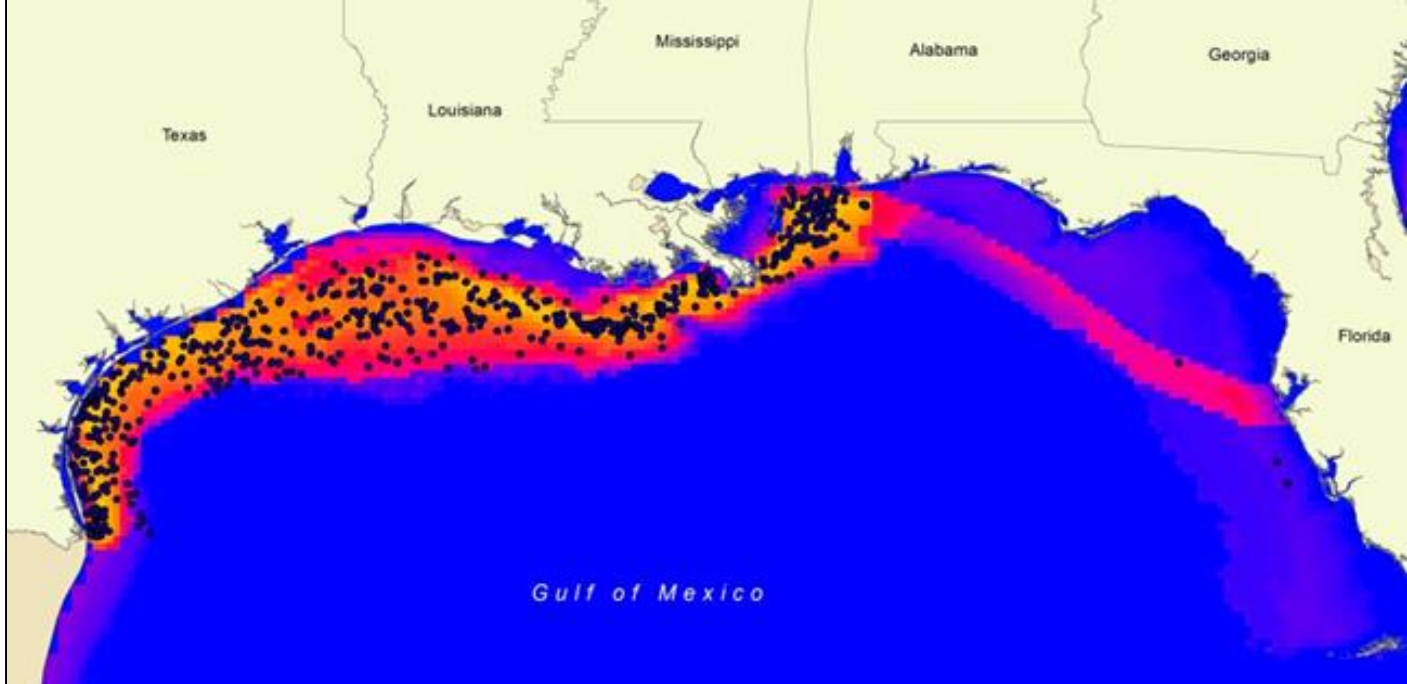
Optimal
Habitat

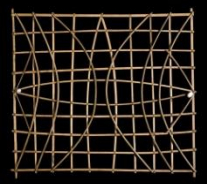


Poor
Habitat



100%
Sample
Points





10%
Sample
Points



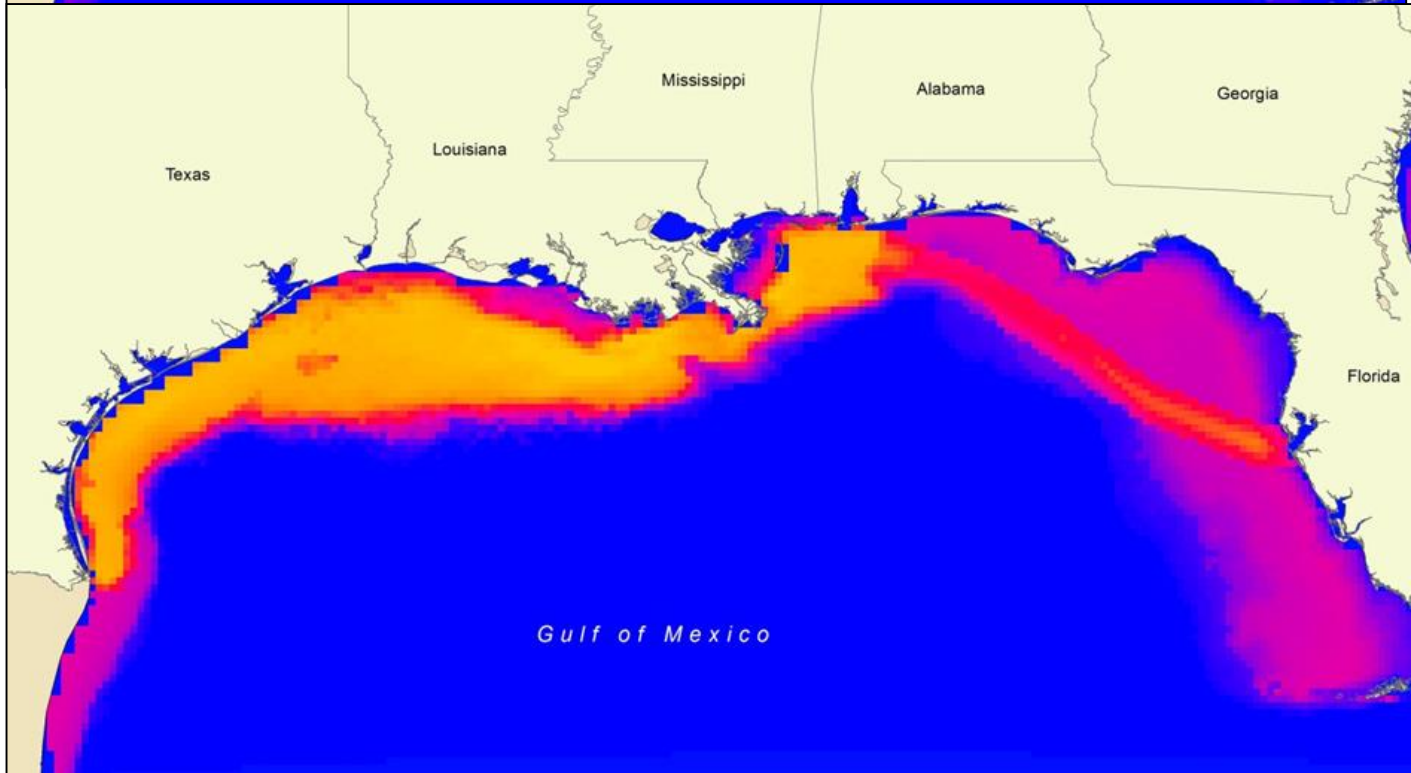
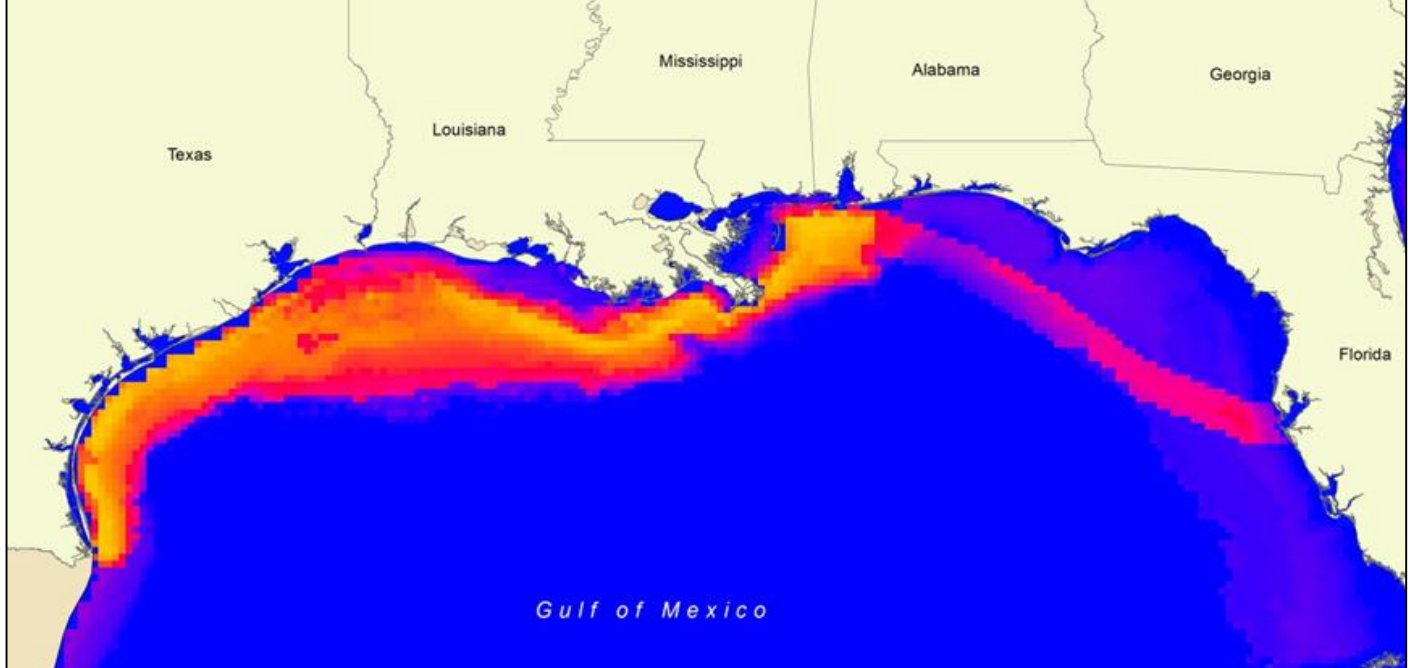
Optimal
Habitat

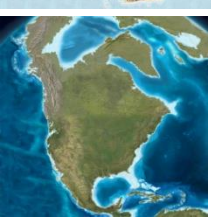
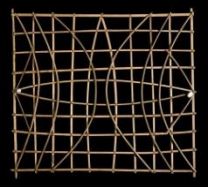


Poor
Habitat

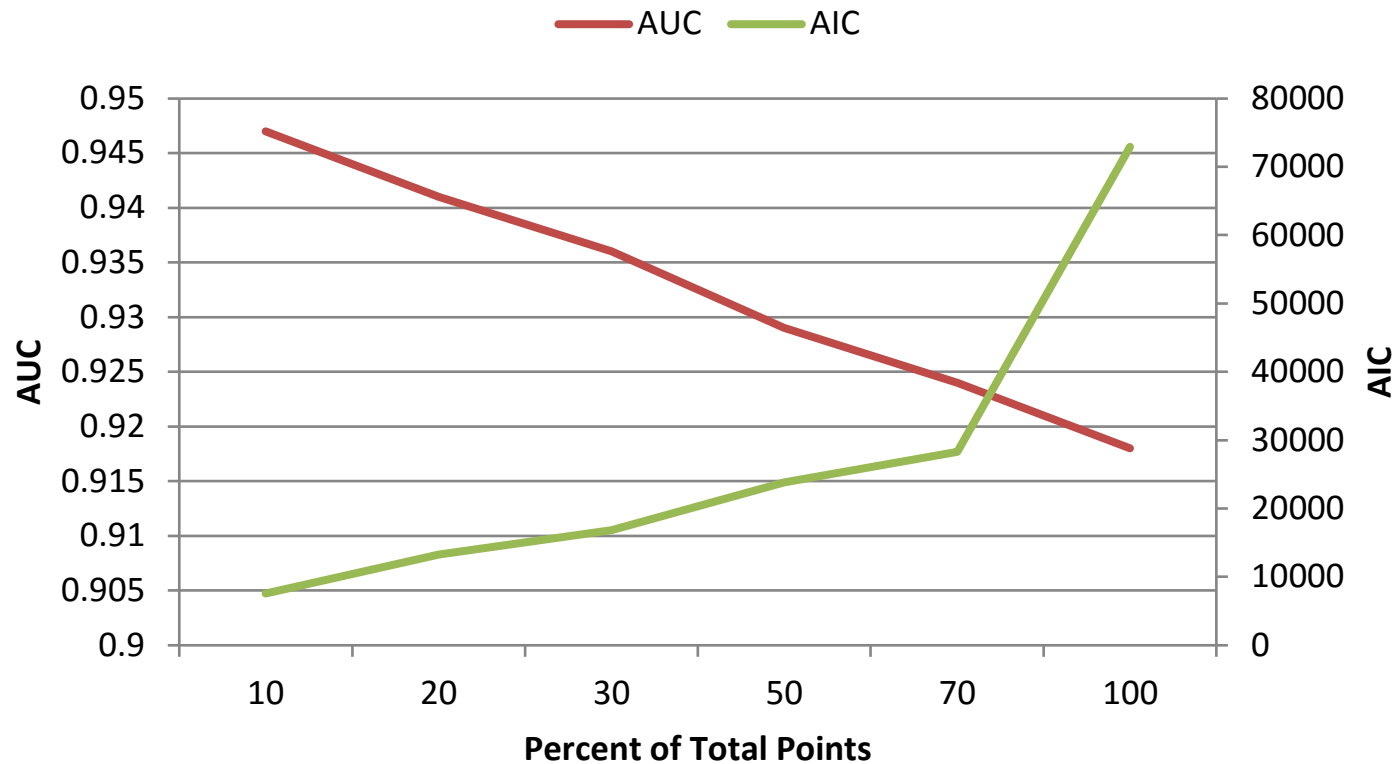


100%
Sample
Points

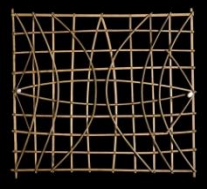




Impact of Sample Points on Performance Measures

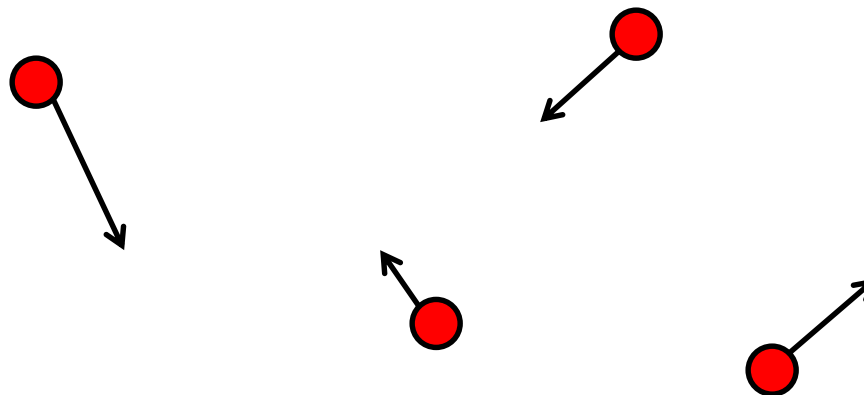


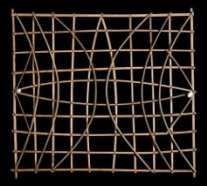
Percent	Number of Samples	Number of Parameters	AIC	AUC
10%	665	136	7549	0.947
20%	1330	166	13,258	0.941
30%	1995	120	16,850	0.936
50%	3326	159	23,839	0.929
70%	4656	162	28,293	0.924
100%	6651	81	72,901	0.918



Jiggling The Samples

- Randomly shifting the position of the points based on a given standard deviation based on sample uncertainty
- Running the model repeatedly to see the potential effect of the uncertainty

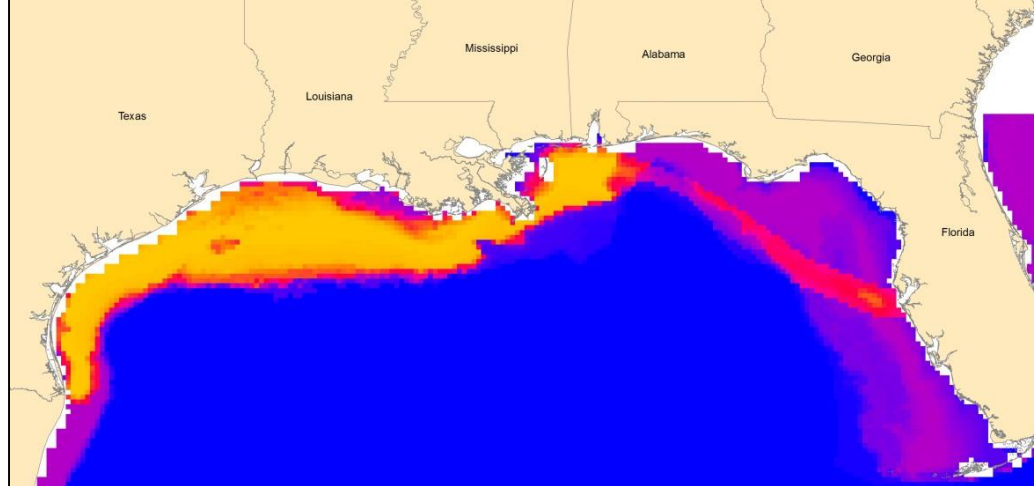




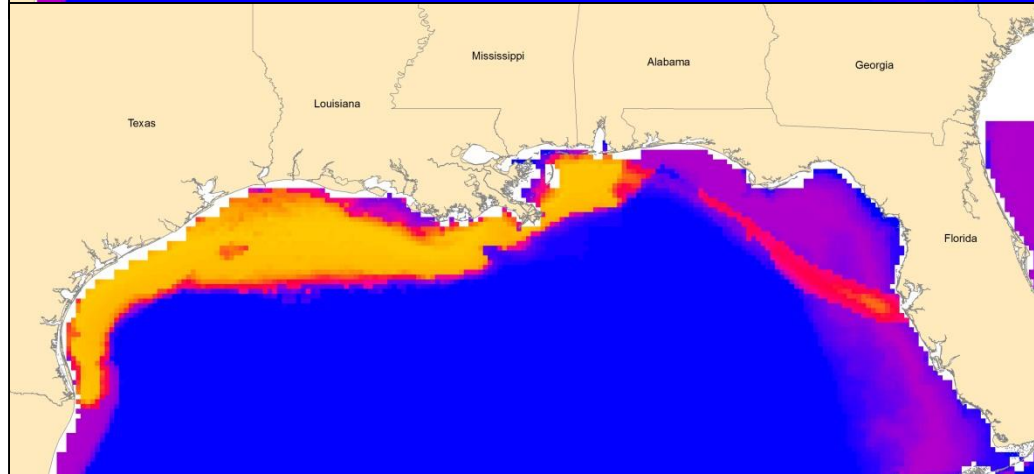
Jiggling



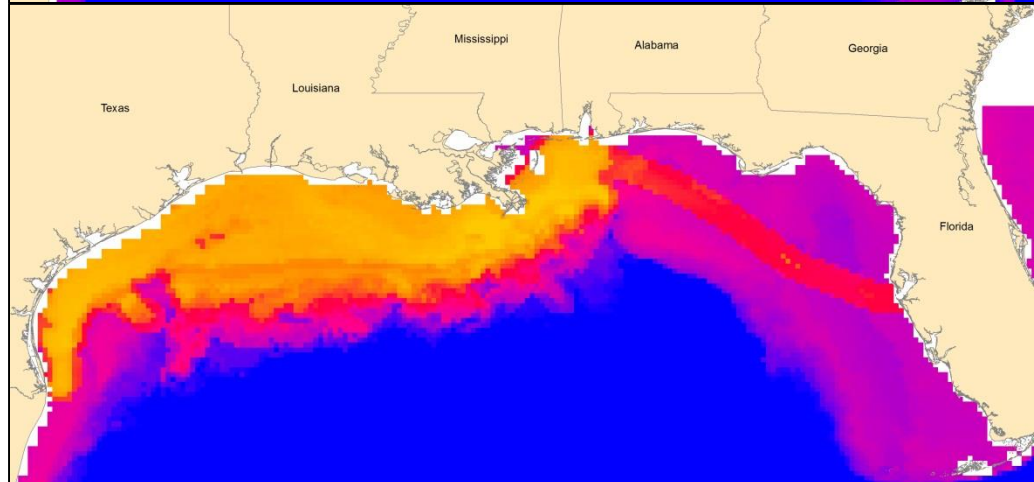
No Jiggling

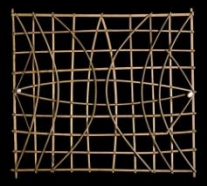


Std Dev=4.4km



Std Dev=55km





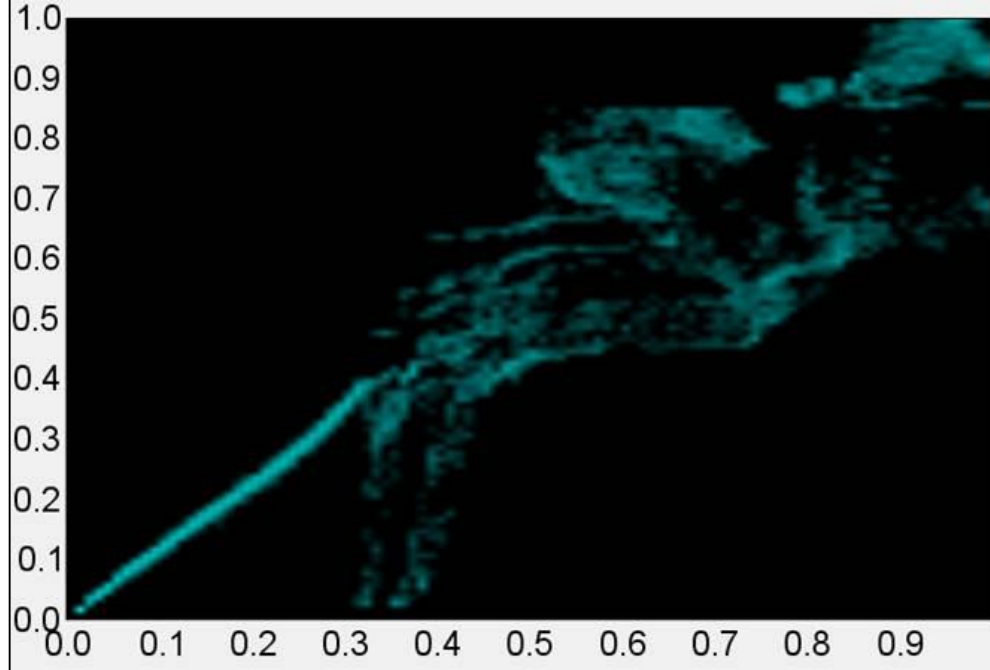
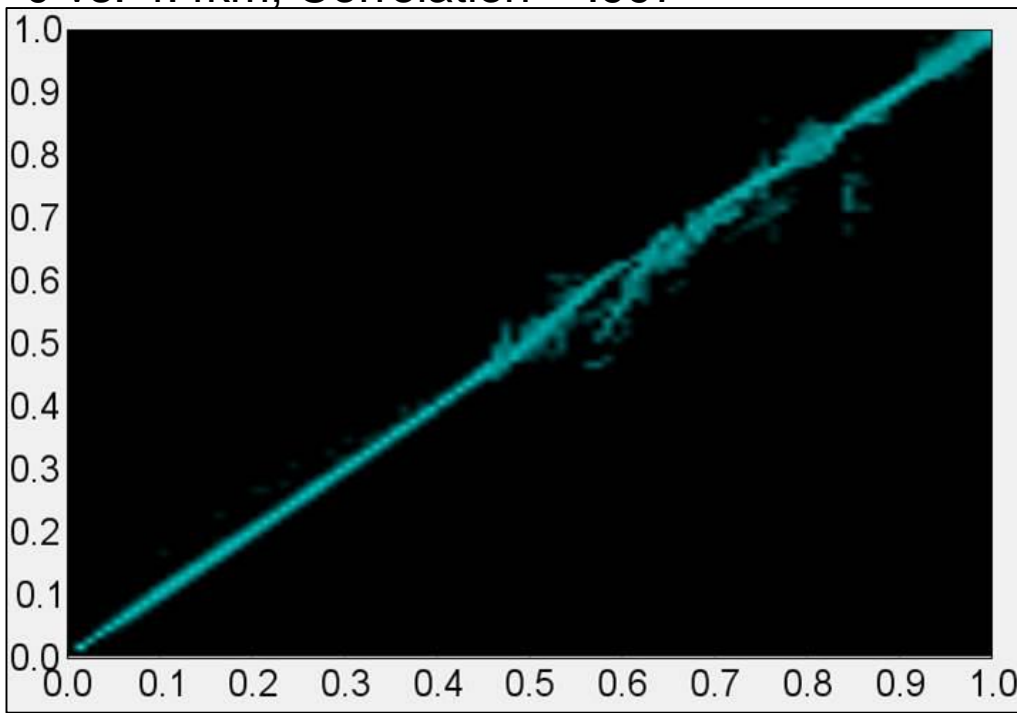
Jiggling



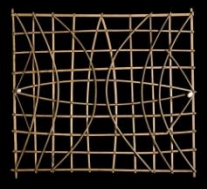
- Spearman's Correlation



0 vs. 4.4km, Correlation = .997

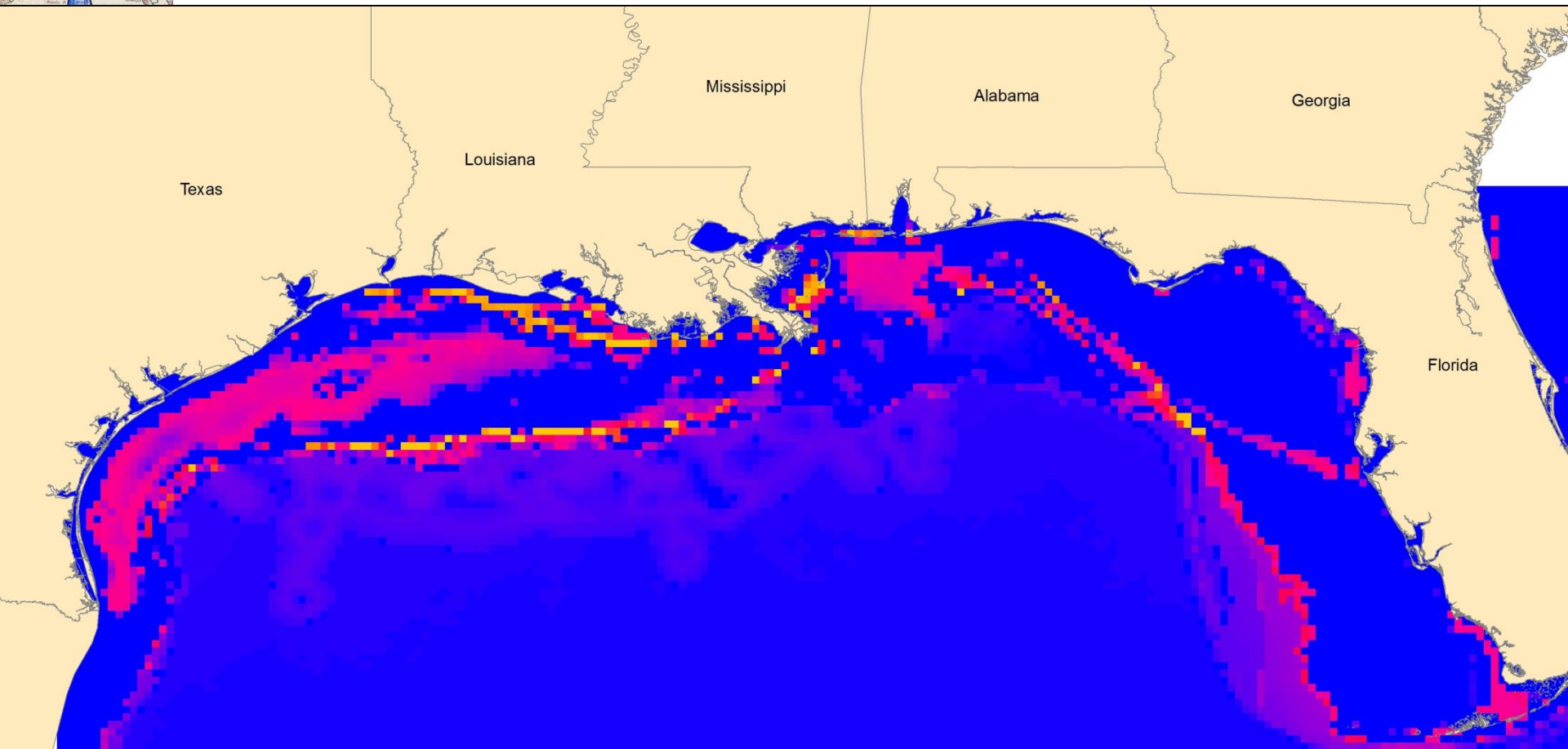


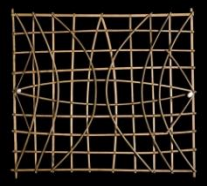
0 vs. 55km, Correlation = .919



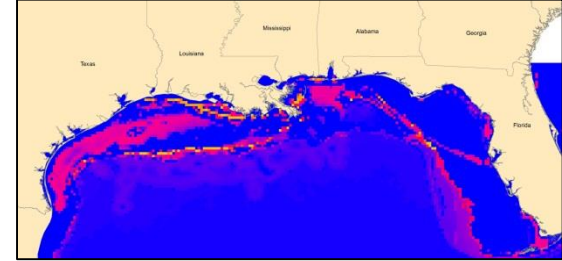
Uncertainty Maps

- Standard Deviation of Jiggling Points by 4.4km



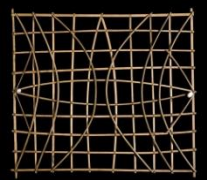


Conclusion



- We can improve HSMs over the default settings in Maxent
- We can determine uncertainty in some cases
- Next Steps
 - Support uncertainty for each data point
 - Improve uncertainty analysis and visualization for predictor layers
 - Begin adding uncertainty analysis and maps to products



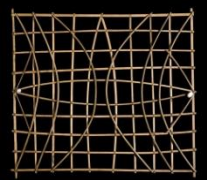


Acknowledgements



- The following individuals helped in the development of these ideas:
 - Greg Newman, Catherine Jarnevich, Thomas Stohlgren, Paul Evangelista
- Colorado State University, Oregon State University, SeaMap, and SchoonerTurtles provided resources for the study



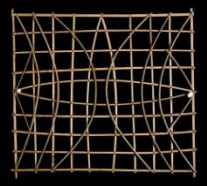


References

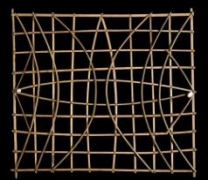


- Anderson, Model Based Inference in the Life Sciences: A Primer on Evidence
- AVHRR Technical Specifications:
http://data.nodc.noaa.gov/pathfinder/Version5.2/GDS_TechSpecs_v2.0.pdf
- Chil's JP, Delfiner P , Geostatistics: Modeling Spatial Uncertainty
- Franklin J, Mapping Species Distributions: Spatial Inference and Prediction. Cambridge University Press, Cambridge
- Hunsaker CT et. al., Spatial Uncertainty in Ecology: Implications for Remote Sensing and GIS Applications
- Maxent: <http://www.cs.princeton.edu/~schapire/maxent/>
- Phillips SJ, Anderson RP, Schapire RE (2006) Maximum entropy modeling of species geographic distributions. Ecol Model 190 (3-4):231-259.
- Warren DL, Seifert SN (2011) Ecological niche modeling in Maxent: the importance of model complexity and the performance of model selection criteria. Ecological Applications 21 (2):335-342.
- Wenzhong S, Principles of Modeling Uncertainties in Spatial Data and Spatial Analyses

Additional Slides



Sources of Uncertainty



Uncertainty?

Protocol Errors, Sampling Bias,
and Instrument Error

Unintended Conversions

Uncertainty increases with
processing, human errors

Incorrect method,
interpretation errors

Representation errors

Interpretation errors

Real World

Measurements

Storage

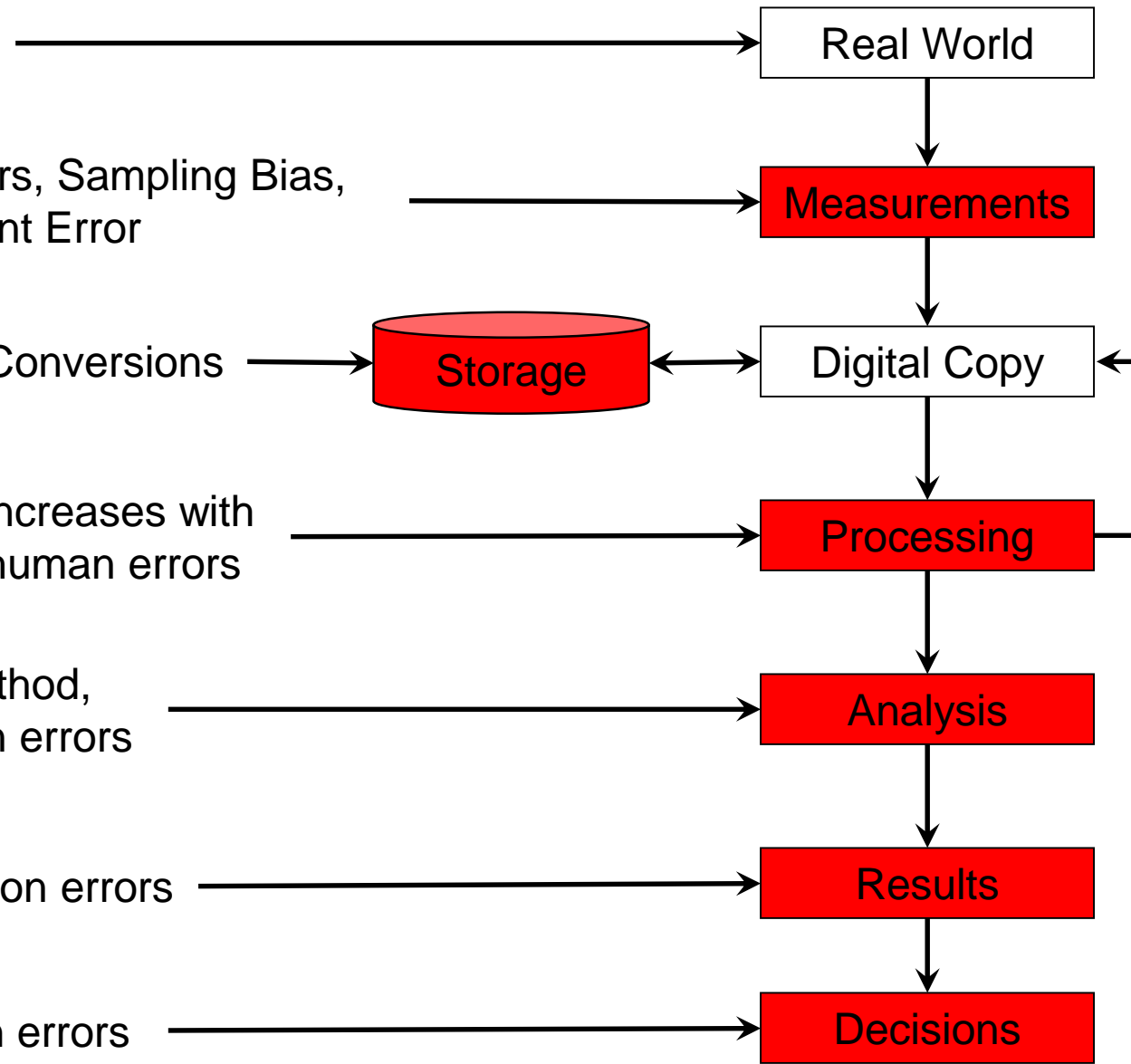
Digital Copy

Processing

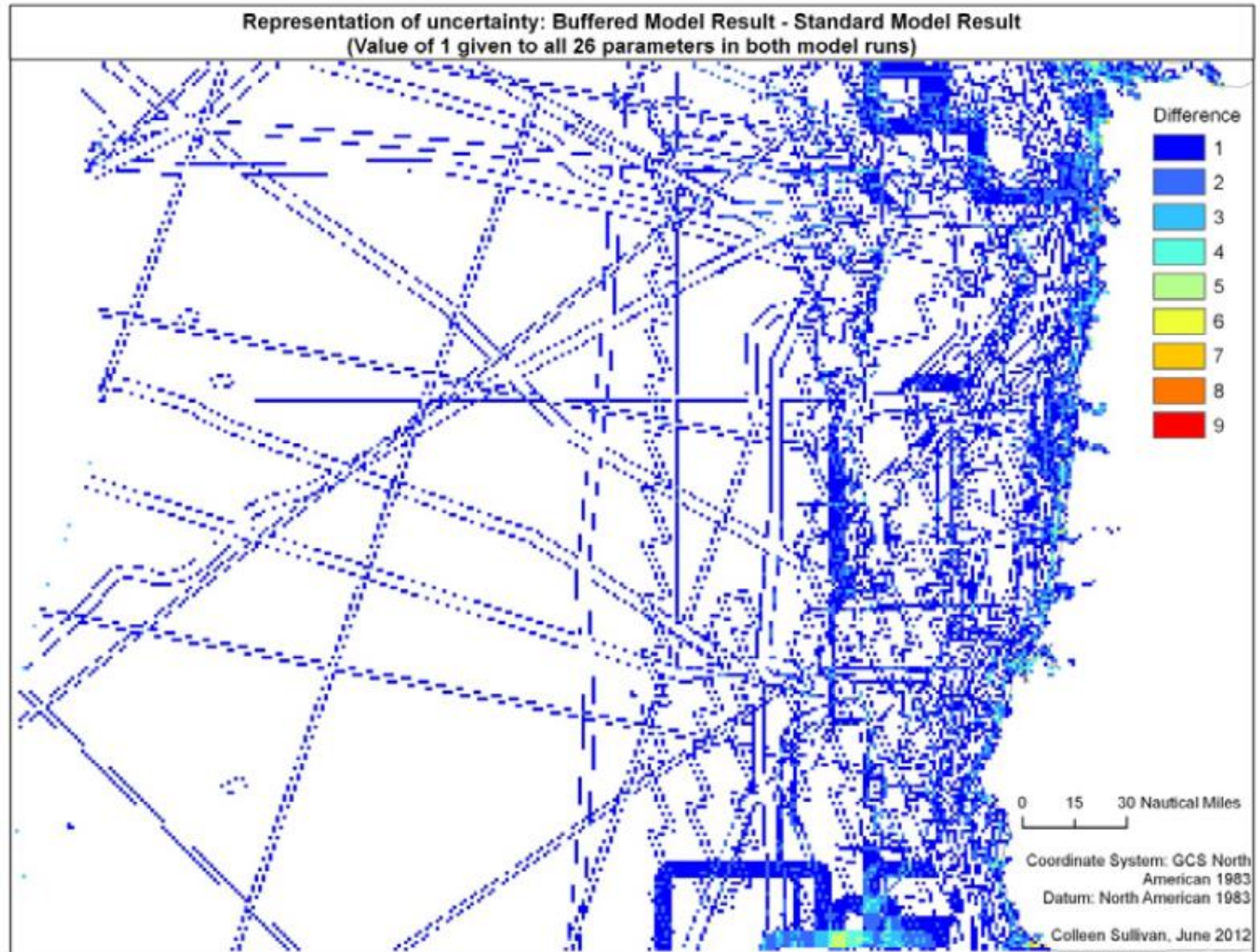
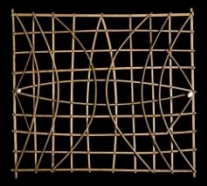
Analysis

Results

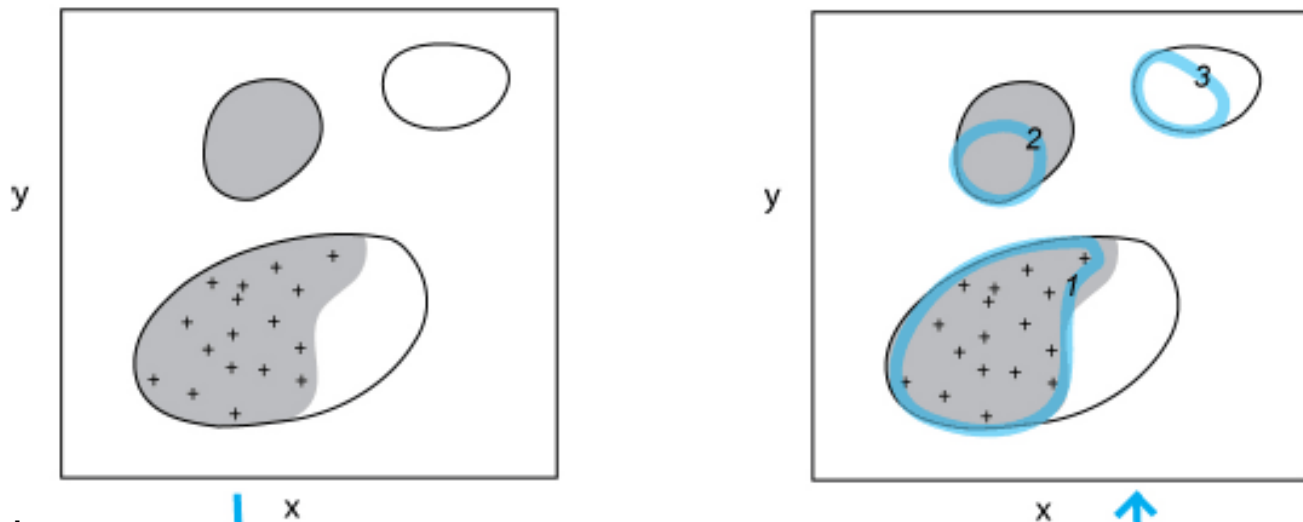
Decisions



Communicating Uncertainty



Geographical Space



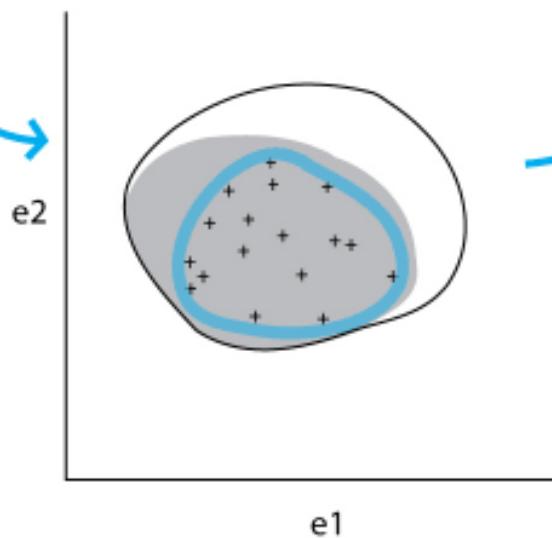
+ Observed Occurrences

● Realized Niche/Distribution

○ Fundamental Niche/Distribution

○ Model Fitted to Occurrences

Environmental Space



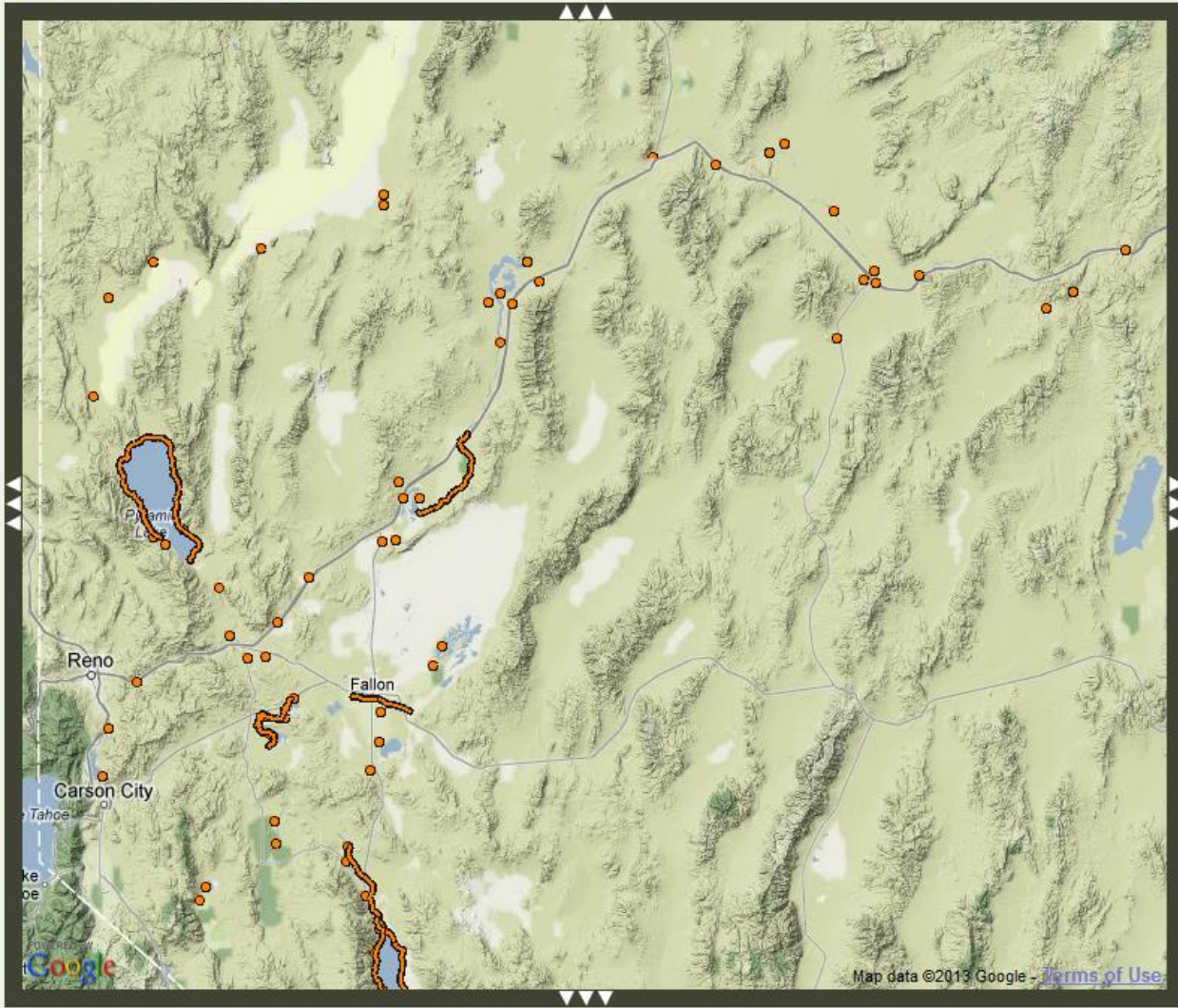
niiss

The National Institute of Invasive Species Science

- Home
- About Us
- Gather Data**
 - Field Methods
 - Field Tools
- Browse Data**
 - By Location
 - By Species
 - By Project
 - By Map
- Contribute Data**
 - Survey Data
 - New Sightings
 - Data Standards
 - GeoRasters
- Download Data**
 - Downloads
 - GeoRasters
- Contact Us
- Help
- Register
- Login

Navigation

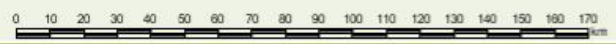
Current Project: [NIISS - General User](#) [Help](#)



Location

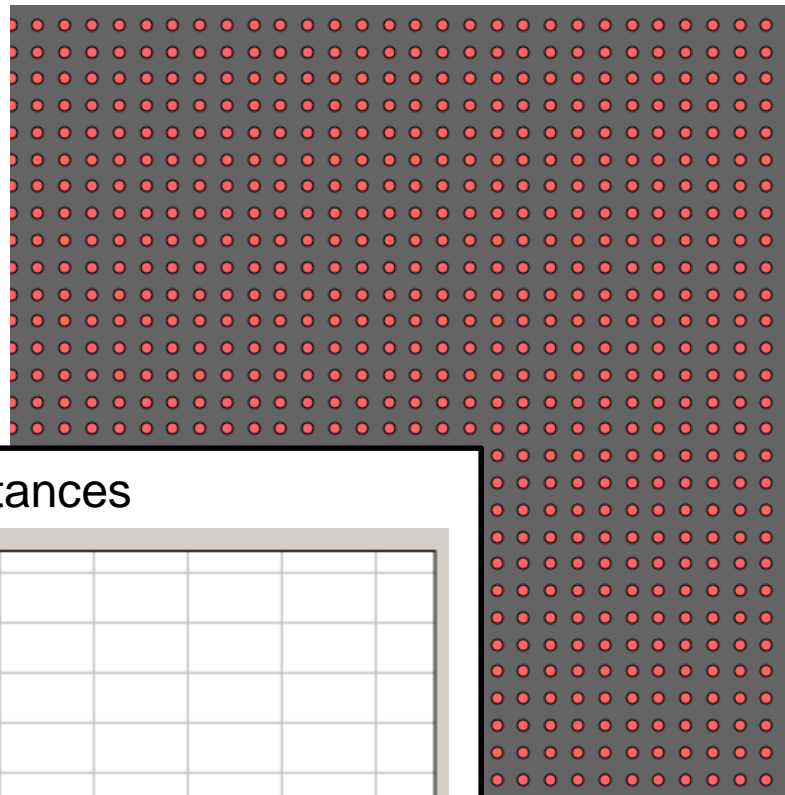
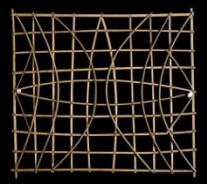
Legend

- Plants
 - Tamarisk
- Backgrounds
 - Google: Terrain
 - Google: Map
 - Google: Satellite
 - Google: Hybrid

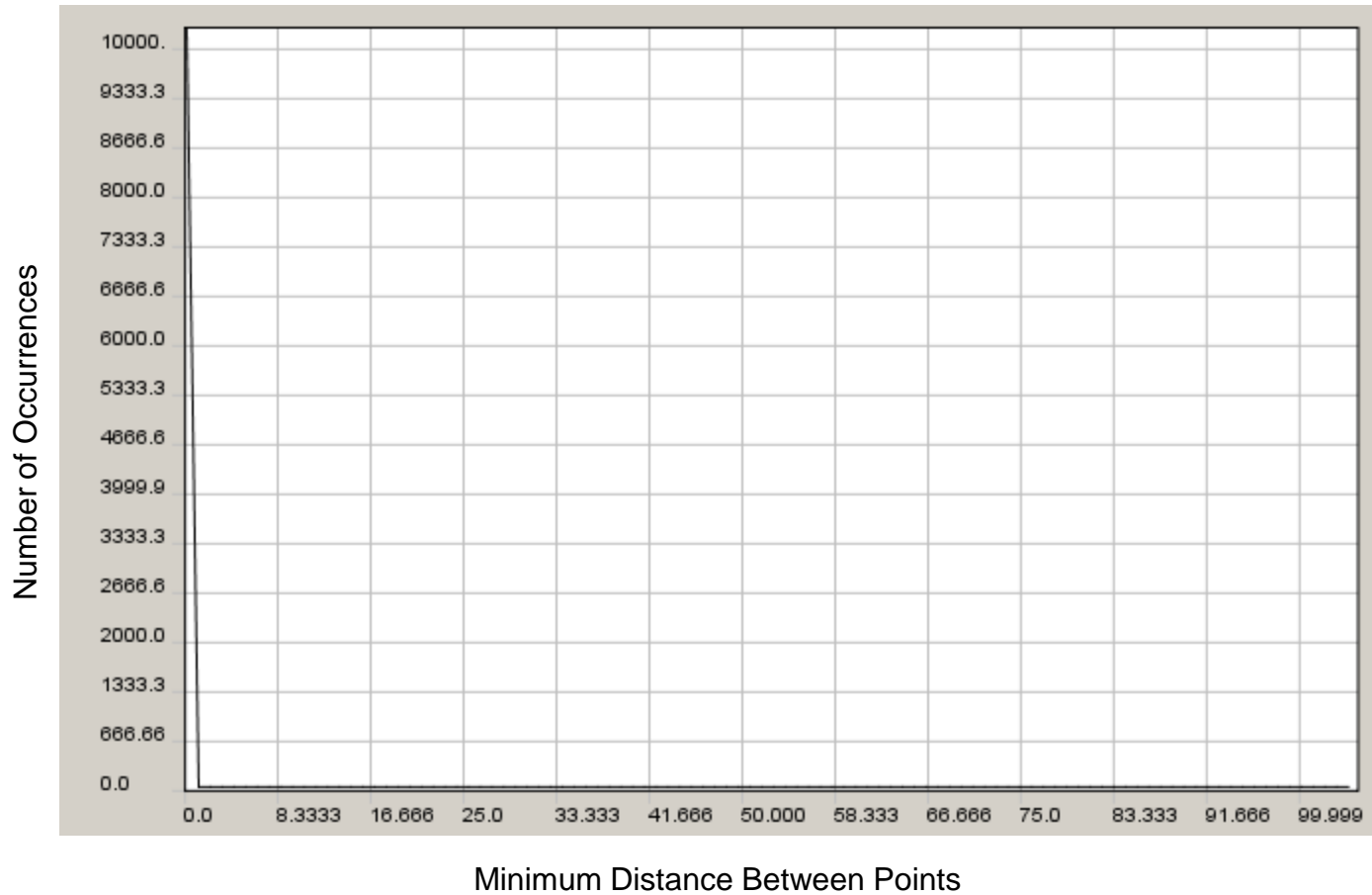


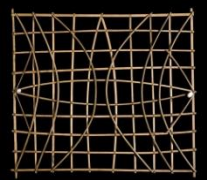
Projection: Google Mercator [Sources](#)

Uniform Data

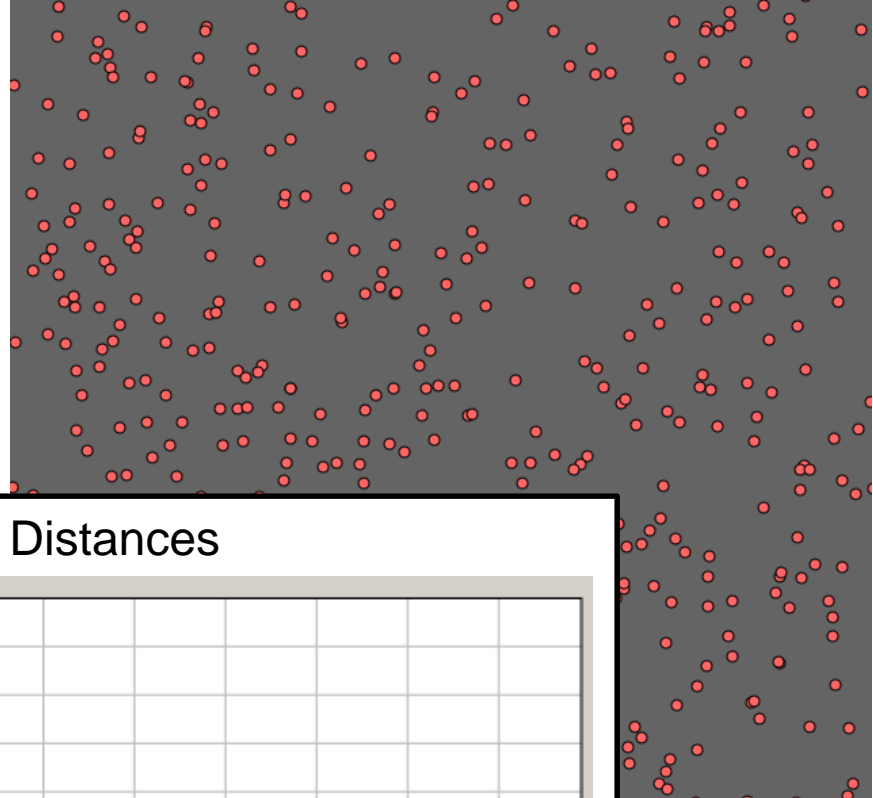


Histogram of Minimum Distances

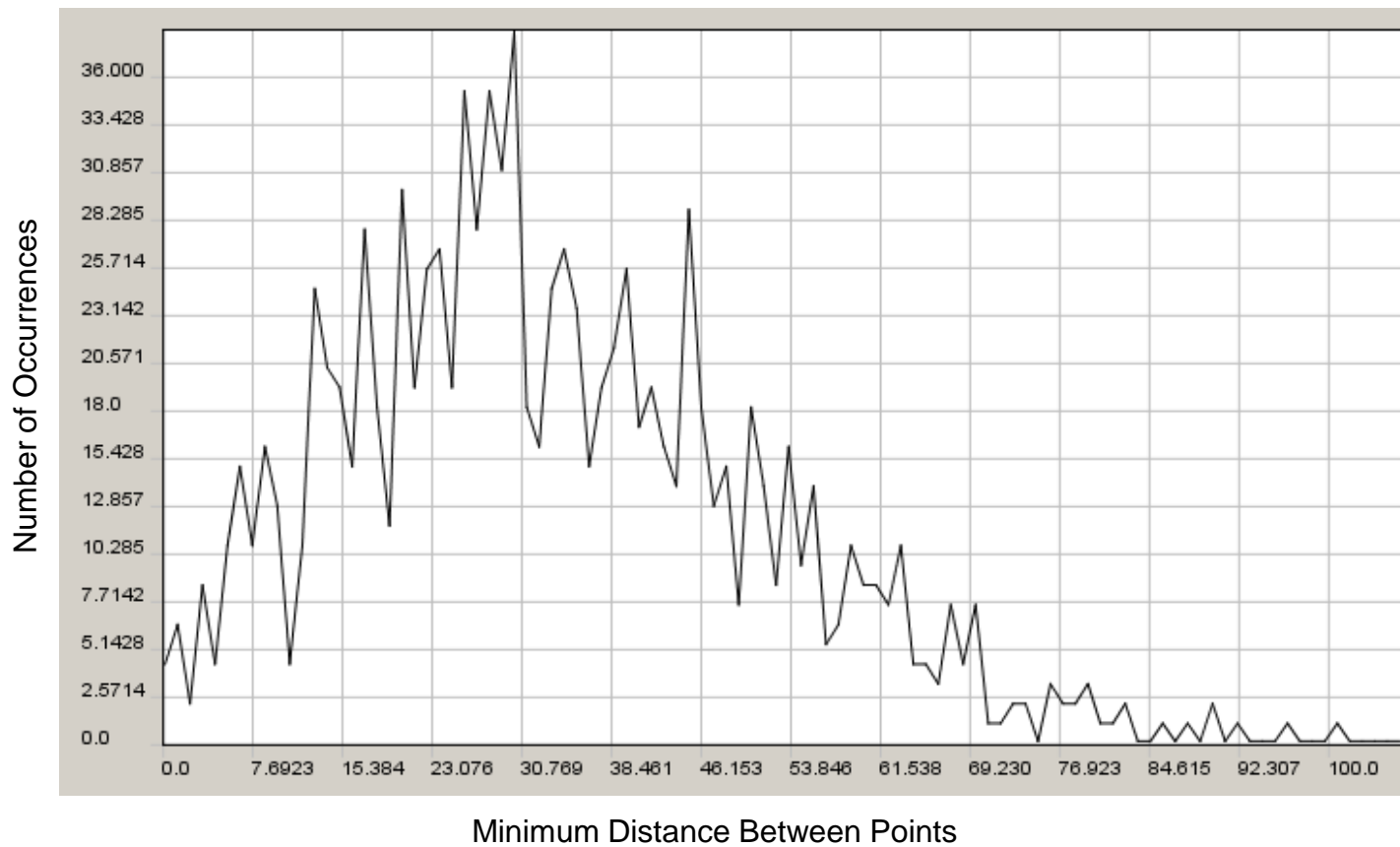


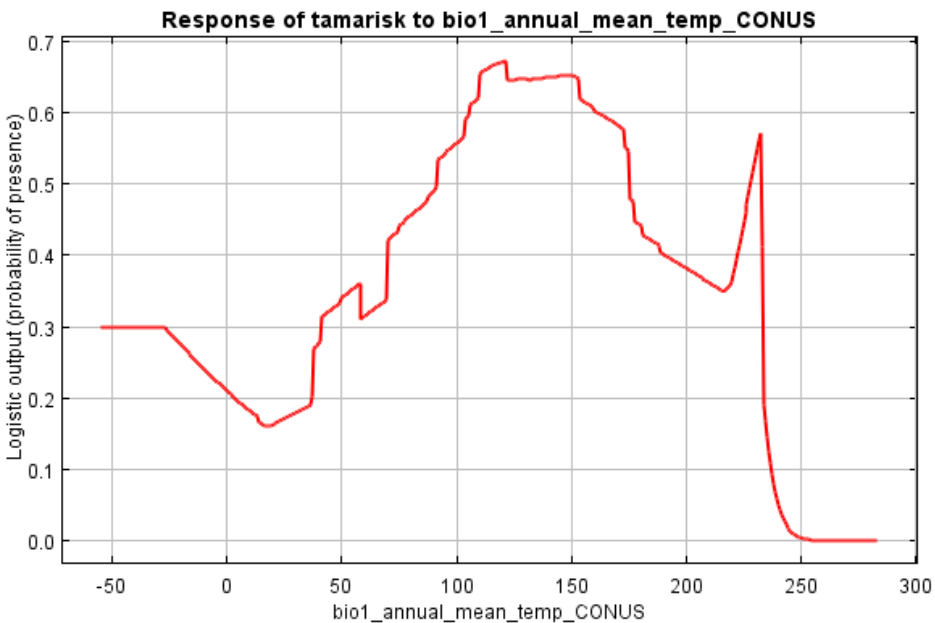


“Random” Data



Histogram of Minimum Distances

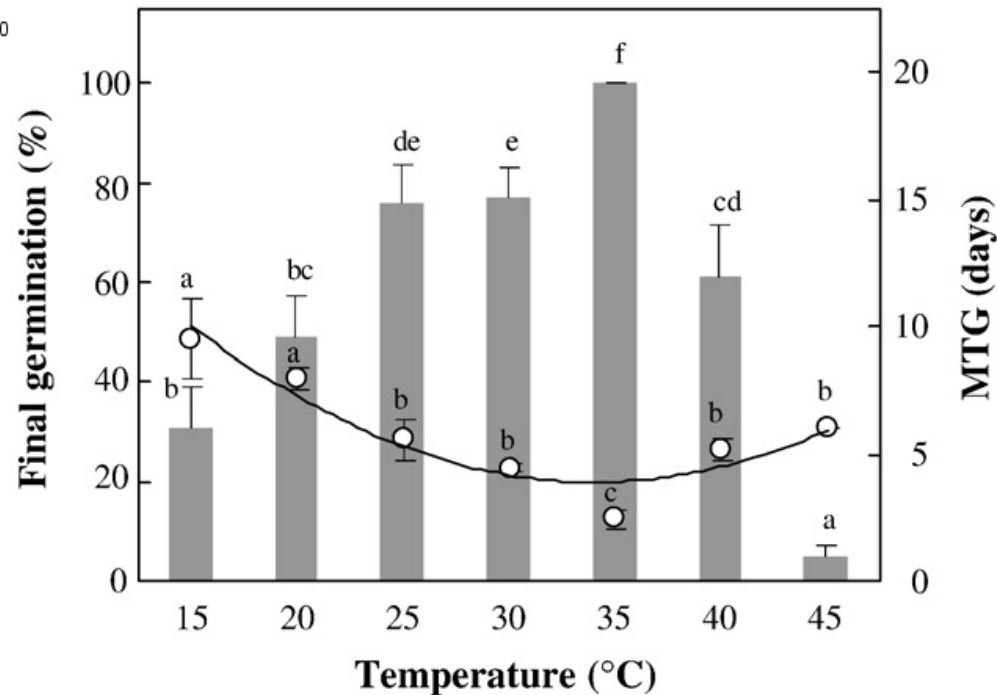


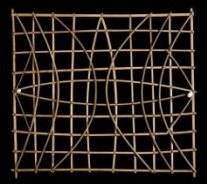


Over-fitting The Data?

Maxent model for *Tamarix* in the US: response to temperature when modeled with temperature and precipitation

What should the model look like?





Staircase of Knowledge

